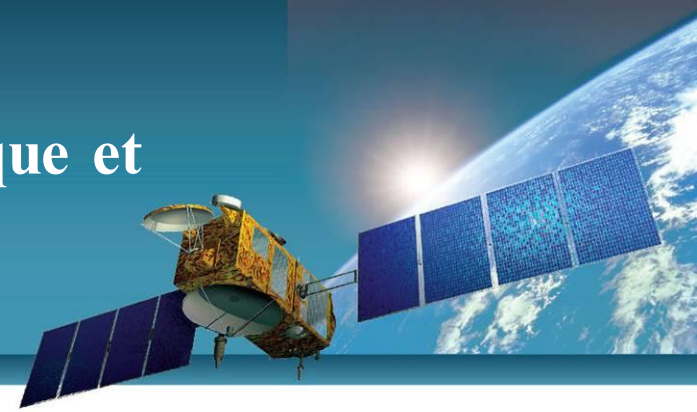




LEGOS

(laboratoire d'études en géophysique et  
océanographie spatiales)



## CMEMS project « Tide – NEMO »

# Implementation of the barotropic tide in the NEMO model

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# HYPOTHESIS (for the methodology to work)

Tide = forced phenomenon predictable by an “inexpensive” model (barotropic)

Accuracy depends on the spatial resolution, bathymetry, SAL, wave drag and optimization of the bottom friction coefficients (possibly by data assimilation)

There is an ideal (= reference/target) solution given by a simplified model (e.g. FES) optimized for tides

! for lack of adapted resolution and optimization based on tides, an OGCM will not give a tide as good as this reference model

! We therefore seek to get as close as possible to the reference solution

⇒ Proposed methodology allows to reproduce the ideal tide model solution projected on the OGCM grid.

⇒ Here Tide model = FES and OGCM = NEMO



# General status of our current work

- Methodology defined

- Implementation in NEMO « done »

  - ⇒ New routine `init_tideFES_dynspg_ts` : based on `dynspg_ts`

  - Calculates fields (projected FES solution `UFES` => `SSH_FES` and forcing fields for momentum)

  - ⇒ Modification of `dynspg_ts` to use the new forcing

  - ⇒ Other subroutines (where tide signal is used) have to be modified too but marginally...

- Tests Configuration « ORCA025 » ( $1/4^\circ$ ) with « academic FES »

- Tests Configuration « ORCA025 » ( $1/4^\circ$ ) with « realistic FES »

  - Underway (interpolation of FES solutions on OGCM grid has to be carefully done)



# METHODOLOGY

Consider 1 mode (solution = linear superimposition of modes)

$$\partial_t \bar{\mathbf{U}}^{TM} + \mathbf{f} \times \bar{\mathbf{U}}^{TM} = -g \nabla \zeta^{TM} + \nabla \Phi_{astro} + \mathbf{X}^{TM},$$

$$\partial_t \zeta^{TM} + \text{div}(H \bar{\mathbf{U}}^{TM}) = 0. \quad \text{Tide model}$$

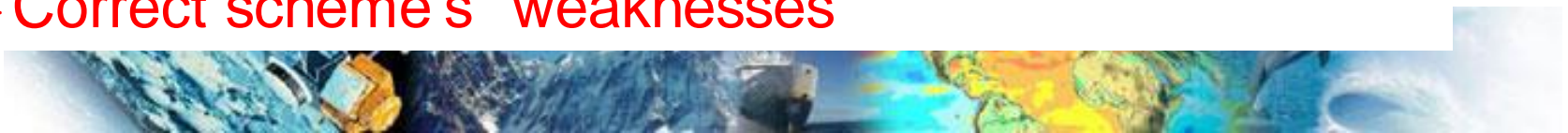
$$\partial_t \bar{\mathbf{U}} + \mathbf{f} \times \bar{\mathbf{U}} = -g \nabla \zeta + \nabla \Phi_{astro} + \overline{\partial_t \mathbf{U}^*} + \mathbf{X},$$

$$\partial_t \zeta + \text{div}((H + \zeta) \bar{\mathbf{U}}) = 0, \quad \text{OGCM, barotropic Eq.}$$

Similar EDP but different implementations/discretization

⇒ Different solutions because of different schemes

⇒ Correct scheme's weaknesses



# METHODOLOGY

**Solution we want to reach (=reference/target)**

$(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$     **Projection of  $(\bar{\mathbf{U}}^{TM}, \zeta^{TM})$  on OGCM grid**

**How must we modify the OGCM schemes to get  $(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$  ?**

$$\partial_t \bar{\mathbf{U}} + \mathbf{f} \times \bar{\mathbf{U}} = -g \nabla \zeta + \nabla \Phi_{astro} + \overline{\partial_t \mathbf{U}^*} + \mathbf{X},$$

$$\partial_t \zeta + \text{div}((H + \zeta) \bar{\mathbf{U}}) = 0,$$



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$$\partial_t \bar{\mathbf{U}} + \mathbf{f} \times \bar{\mathbf{U}} = -g \nabla \zeta + \nabla \Phi_{astro} + \overline{\partial_t \mathbf{U}^*} + \mathbf{X},$$

$$\partial_t \zeta + \text{div}((H + \cancel{s}) \bar{\mathbf{U}}) = 0,$$

**linearize**

**gather these terms into 1 term**

**FOM**



# METHODOLOGY

**Solution we want to reach (=reference/target)**

$(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$     **Projection of  $(\bar{\mathbf{U}}^{TM}, \zeta^{TM})$  on OGCM grid**

**How must we modify the OGCM schemes to get  $(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$  ?**

**$\zeta^{OM}$  and  $\mathbf{F}^{OM}$  are « readily » determined ...**

$$\partial_t \bar{\mathbf{U}}^{OM} + \mathbf{f} \times \bar{\mathbf{U}}^{OM} - g \nabla \zeta^{OM} = \mathbf{F}^{OM},$$

$$\partial_t \zeta^{OM} + \text{div}(H \bar{\mathbf{U}}^{OM}) = 0.$$



# METHODOLOGY

**Solution we want to reach (=reference/target)**

$(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$  Projection of  $(\bar{\mathbf{U}}^{TM}, \zeta^{TM})$  on OGCM grid

How must we modify the OGCM schemes to get  $(\bar{\mathbf{U}}^{OM}, \zeta^{OM})$  ?

$\zeta^{OM}$  and  $\mathbf{F}^{OM}$  are « readily » determined ...

$$\partial_t \bar{\mathbf{U}}^{OM} + \mathbf{f} \times \bar{\mathbf{U}}^{OM} - g \nabla \zeta^{OM} = \mathbf{F}^{OM}, \text{ IMPORTANT Discretized Operators}$$

$$\partial_t \zeta^{OM} + \text{div}(H \bar{\mathbf{U}}^{OM}) = 0. \Rightarrow \zeta^{OM} \text{ \& } \mathbf{F}^{OM} \text{ adapted to numerical schemes}$$





# METHODOLOGY

## In practice

Determine the (projected) **TRANSPORT** and split into cos/sin

$$(\overline{H\bar{U}})^{OM}(x, y, t) = (\overline{H\bar{U}})_c^{OM}(x, y) \cos \omega t + (\overline{H\bar{U}})_s^{OM}(x, y) \sin \omega t$$

### OGCM SSH Eq

$$\zeta_{N+1} = Op_t[\zeta_N, \zeta_{N-1}, \zeta_{N-2}] + Op_{x/y}[(\overline{H\bar{U}})_{N+1}, (\overline{H\bar{U}})_N, (\overline{H\bar{U}})_{N-1}, (\overline{H\bar{U}})_{N-2}] \quad (7)$$

$Op_t[.]$  and  $Op_{x/y}[.]$  are discretized time and spatial operator

$$\zeta^{OM}(x, y, t) = \zeta_c^{OM}(x, y) \cos \omega t + \zeta_s^{OM}(x, y) \sin \omega t$$



# METHODOLOGY

# In practice

$$\begin{bmatrix} \alpha_c & \alpha_s \\ \beta_c & \beta_s \end{bmatrix} \times \begin{pmatrix} \zeta_c^{OM} \\ \zeta_s^{OM} \end{pmatrix} = \begin{pmatrix} Div_c^{tot} \\ Div_s^{tot} \end{pmatrix}$$

$$\begin{aligned} \alpha_c &= \cos(\omega\Delta t) - Op_t[1, \cos(-\omega\Delta t), \cos(-\omega 2\Delta t)] \\ \beta_c &= \cos(\frac{\pi}{2} + \omega\Delta t) - Op_t[0, \cos(\frac{\pi}{2} - \omega\Delta t), \cos(\frac{\pi}{2} - \omega 2\Delta t)] \\ \alpha_s &= -\beta_c \\ \beta_s &= \alpha_c \end{aligned}$$

$$\begin{aligned} Div_c^{tot} &= Op_{x/y}[(H\bar{U})_c, 0, 0, 0] \cos(\omega\Delta t) \\ &+ Op_{x/y}[0, (H\bar{U})_c, 0, 0] (1) \\ &+ Op_{x/y}[0, 0, (H\bar{U})_c, 0] \cos(\omega\Delta t) \\ &+ Op_{x/y}[0, 0, 0, (H\bar{U})_c] \cos(\omega\Delta t) \\ &+ Op_{x/y}[(H\bar{U})_c, 0, 0, 0] (-\sin(\omega\Delta t)) \\ &+ Op_{x/y}[0, (H\bar{U})_c, 0, 0] (0) \\ &+ Op_{x/y}[0, 0, (H\bar{U})_c, 0] (-\sin(\omega\Delta t)) \\ &+ Op_{x/y}[0, 0, 0, (H\bar{U})_c] (-\sin(2\omega\Delta t)) \end{aligned}$$

$$\begin{aligned} Div_s^{tot} &= Op_{x/y}[(H\bar{U})_s, 0, 0, 0] \cos(\omega\Delta t) \\ &+ Op_{x/y}[0, (H\bar{U})_s, 0, 0] \cos(\omega\Delta t) \\ &+ Op_{x/y}[0, 0, (H\bar{U})_s, 0] \cos(\omega\Delta t) \\ &+ Op_{x/y}[0, 0, 0, (H\bar{U})_s] \cos(2\omega\Delta t) \\ &+ Op_{x/y}[(H\bar{U})_s, 0, 0, 0] (-\sin(\omega\Delta t)) \\ &+ Op_{x/y}[0, (H\bar{U})_s, 0, 0] (0) \\ &+ Op_{x/y}[0, 0, (H\bar{U})_s, 0] (\sin(\omega\Delta t)) \\ &+ Op_{x/y}[0, 0, 0, (H\bar{U})_s] (\sin(2\omega\Delta t)). \end{aligned}$$

**Clumsy expressions, but solution determined from a single time step run of the barotropic scheme**



# METHODOLOGY

## In practice

$$\mathbf{F}^{OM} = \bar{\mathbf{U}}_{N+1}^{OM} - Op_t[\bar{\mathbf{U}}_N^{OM}, \bar{\mathbf{U}}_{N-1}^{OM}, \bar{\mathbf{U}}_{N-2}^{OM}] \\ - Op_{x/y}[(\bar{\mathbf{U}}^{OM}, \zeta^{OM})_{N+1}, (\bar{\mathbf{U}}^{OM}, \zeta^{OM})_N, (\bar{\mathbf{U}}^{OM}, \zeta^{OM})_{N-1}, \dots]$$

**Similar approach to calculate the forcing terms ...  
(even more clumsy expressions but exact and adapted  
to chosen numerical schemes)**



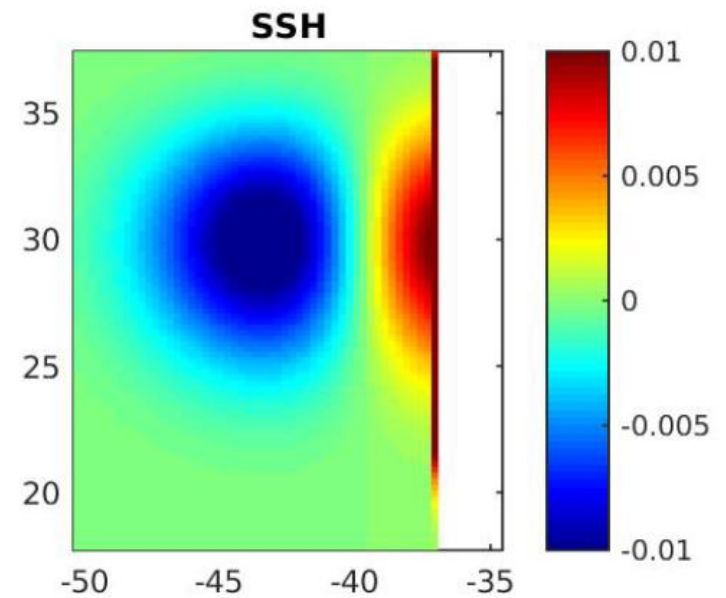
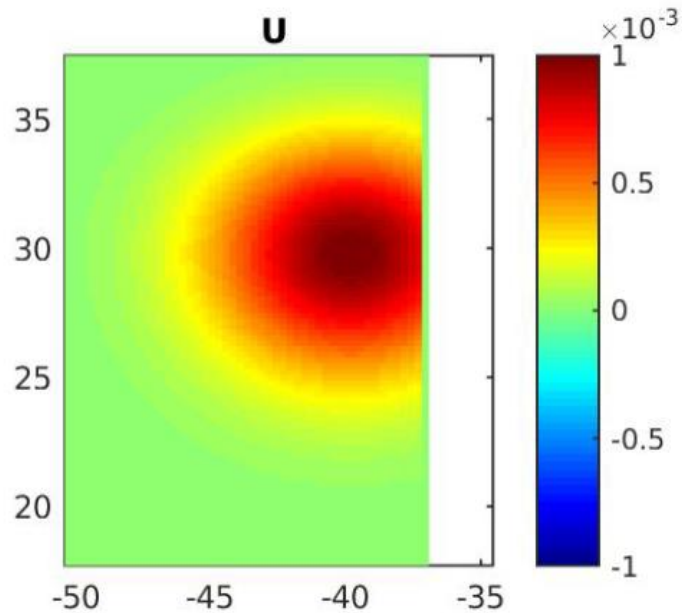
# Results with academic fields

$$H\bar{U}_s^{OM} = HU_0 \exp\left(-\frac{(x-x_0)^2 + (y-y_0)^2}{R^2}\right),$$

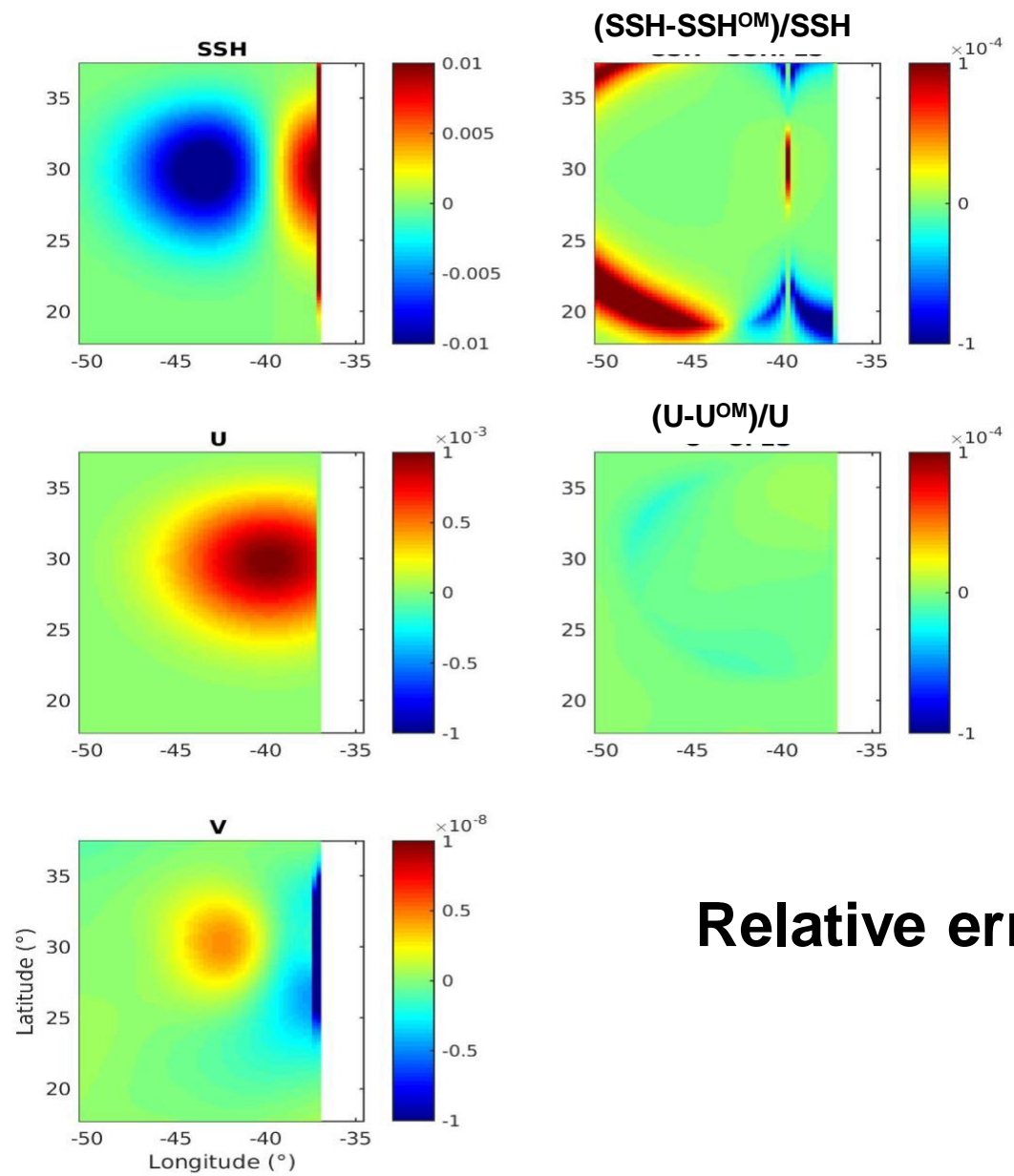
$$H\bar{V}_s^{OM} = 0,$$

$$H\bar{U}_c^{OM} = 0,$$

$$H\bar{V}_c^{OM} = 0$$



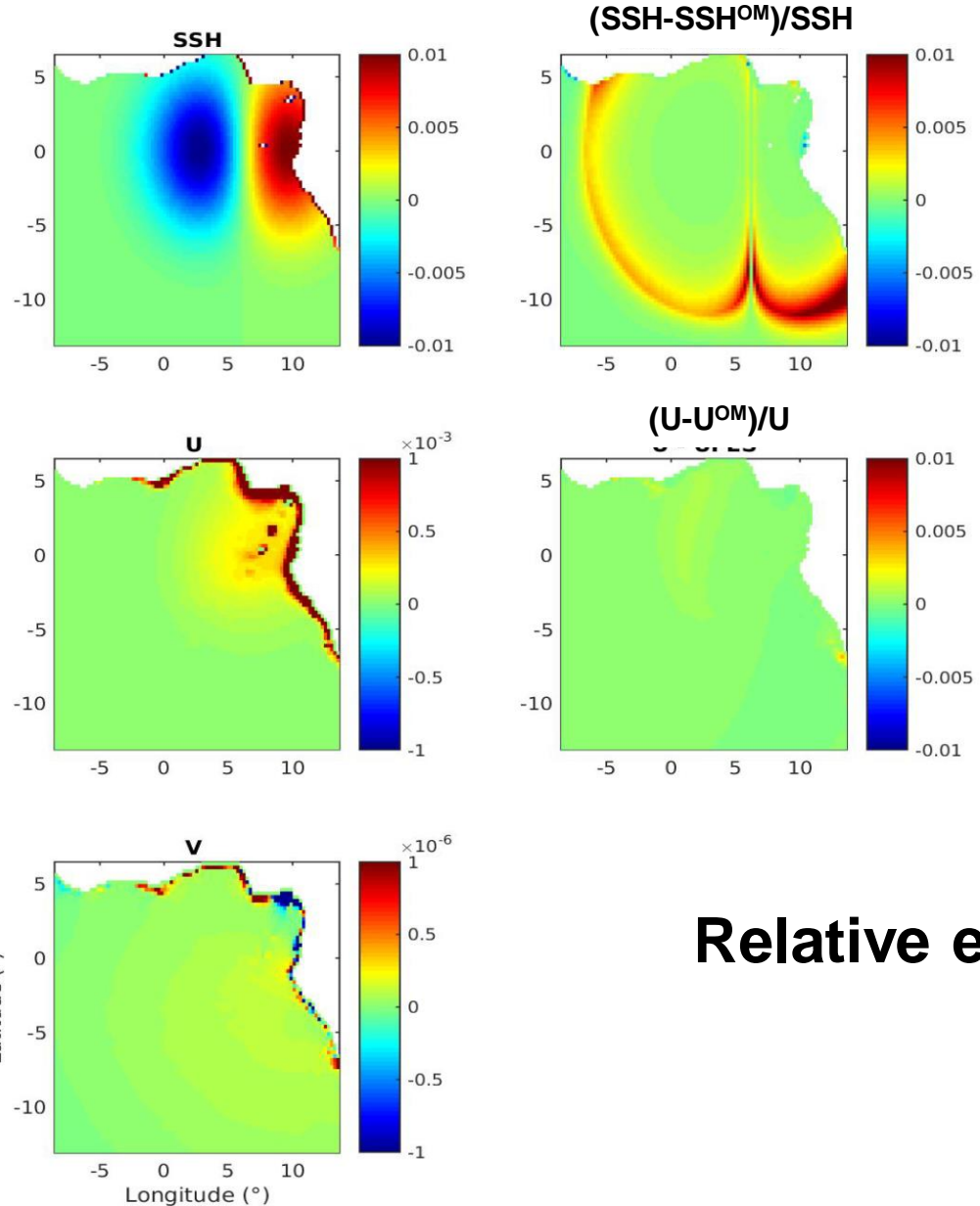
# Results with academic fields



**Relative error = very weak**



# Results with academic fields

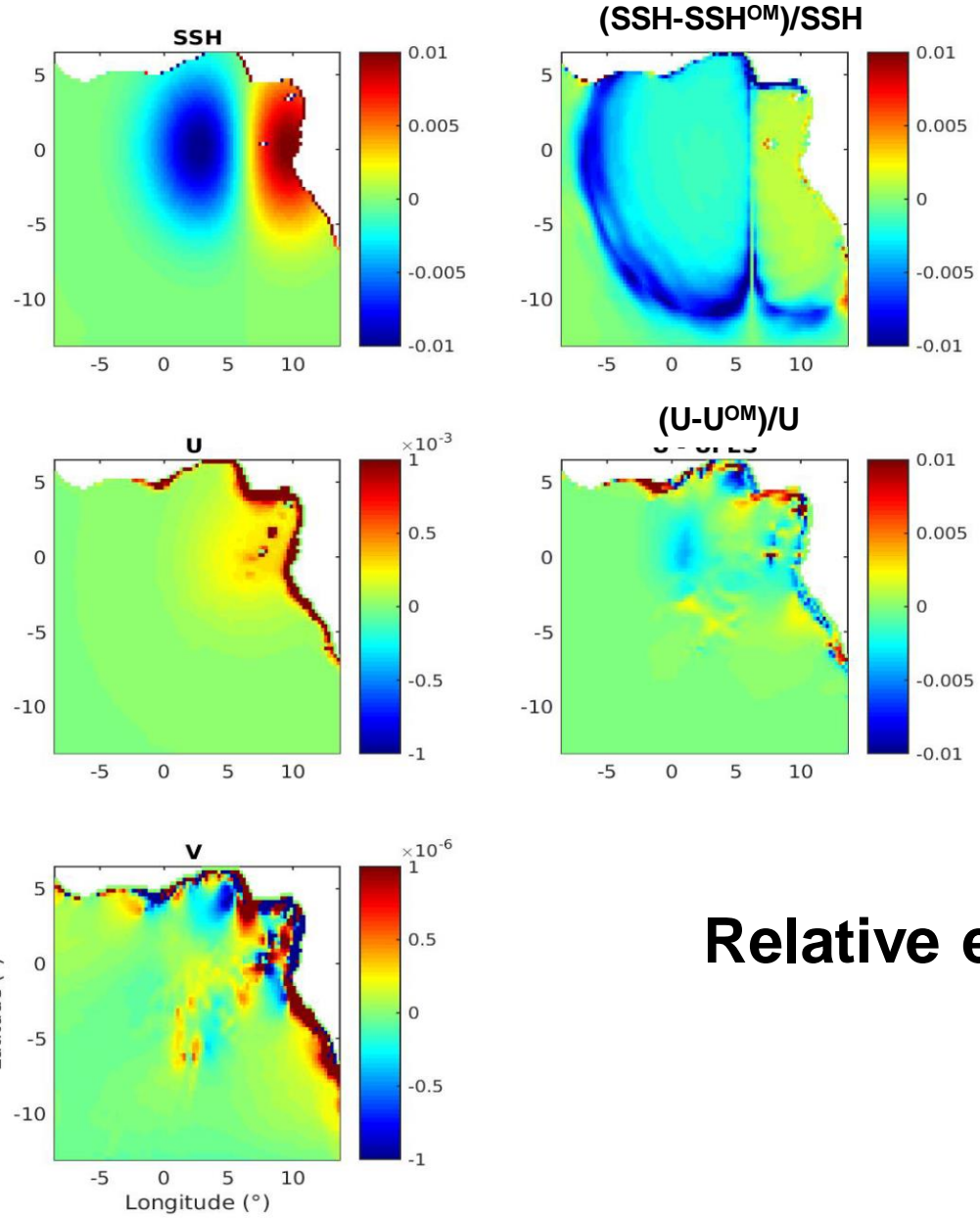


**Academic  
+Realistic topography**

**Relative error = very weak**



# Results with academic fields



**Academic  
+Realistic topography  
+nonlinear terms**

**Relative error = very weak**

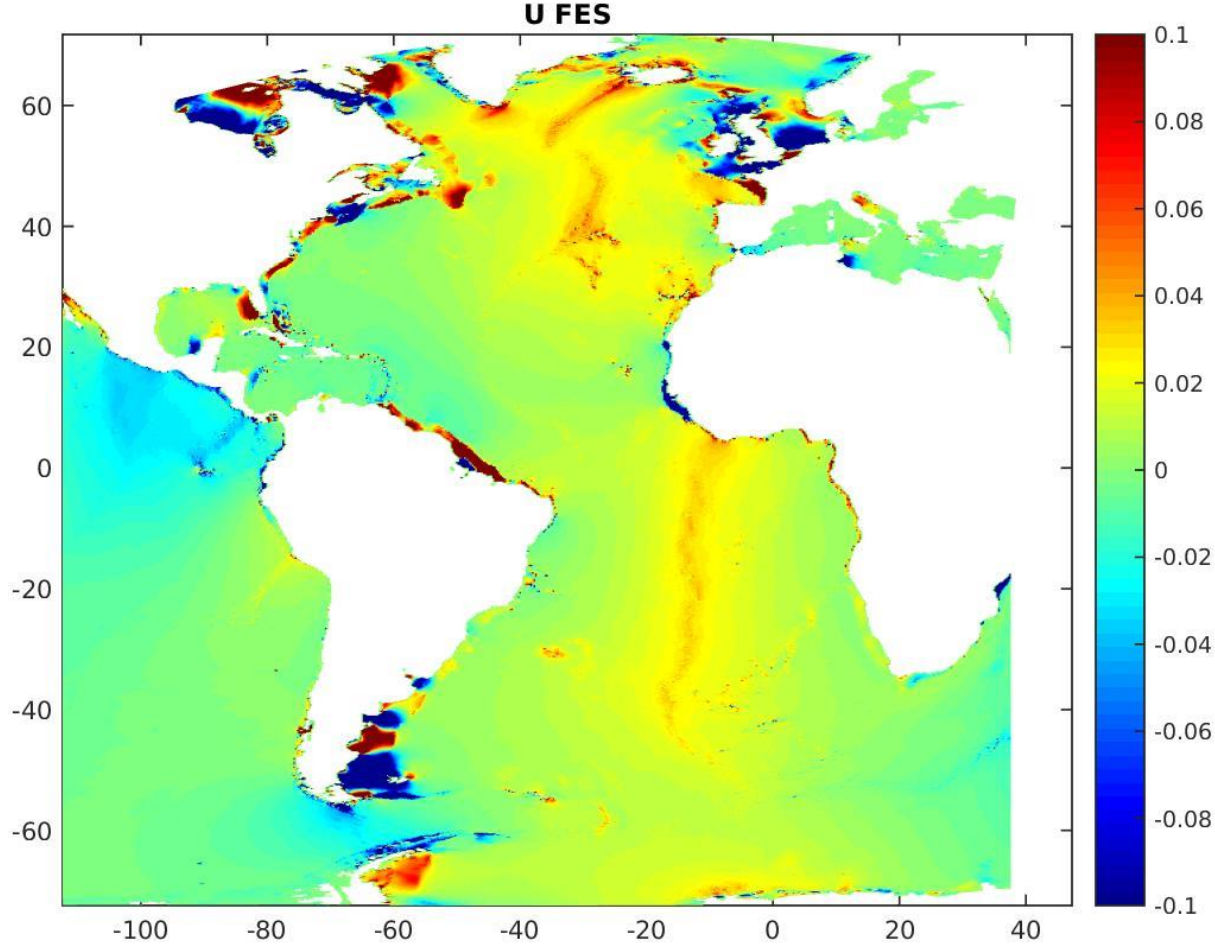


# Results with real FES fields (M2)

FES Solution interpolated  
On single NEMO grid point

$$U = \text{Transport/Depth(NEMO)}$$

**Current work**

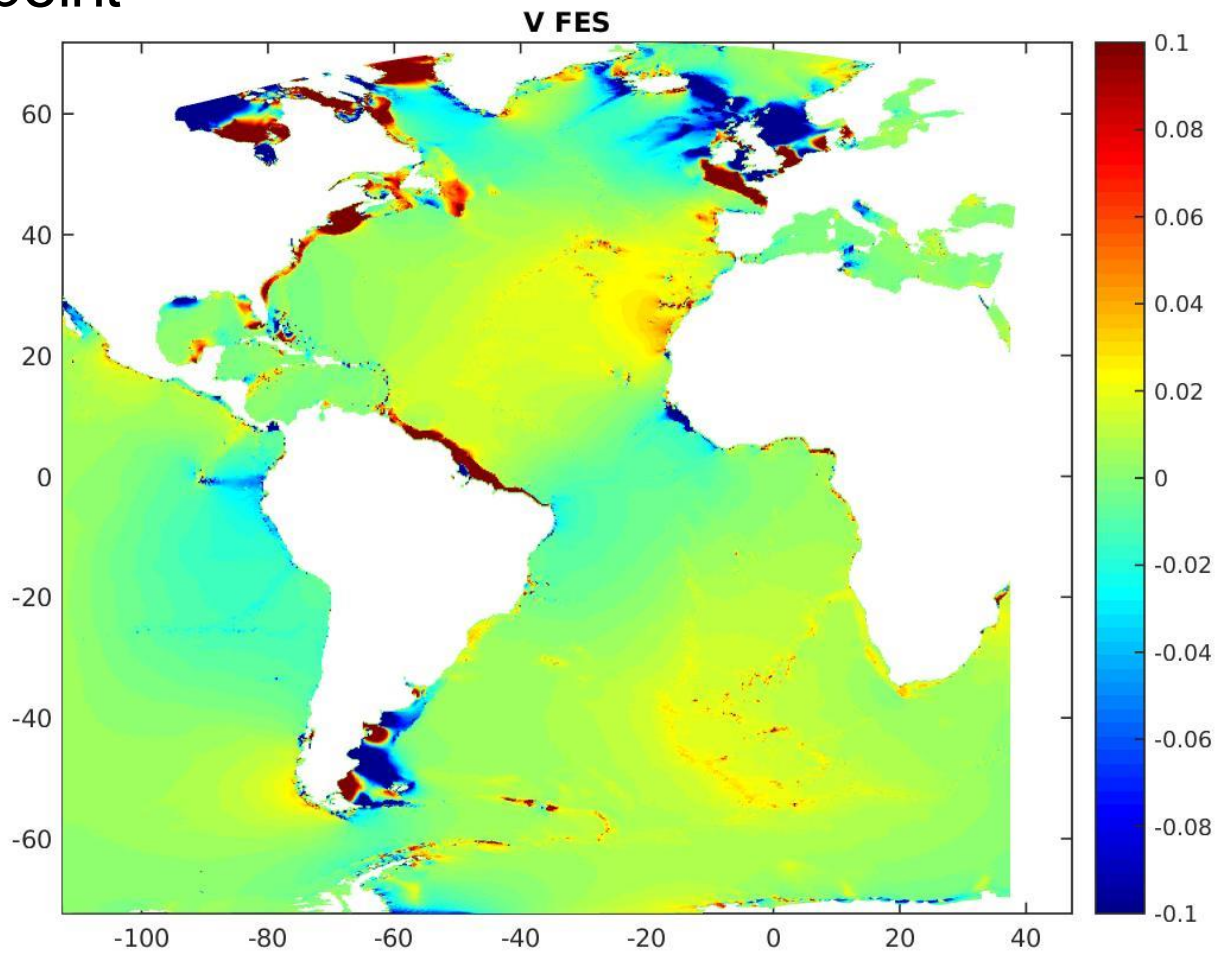




# Results with real FES fields

FES Solution interpolated  
On single NEMO grid point

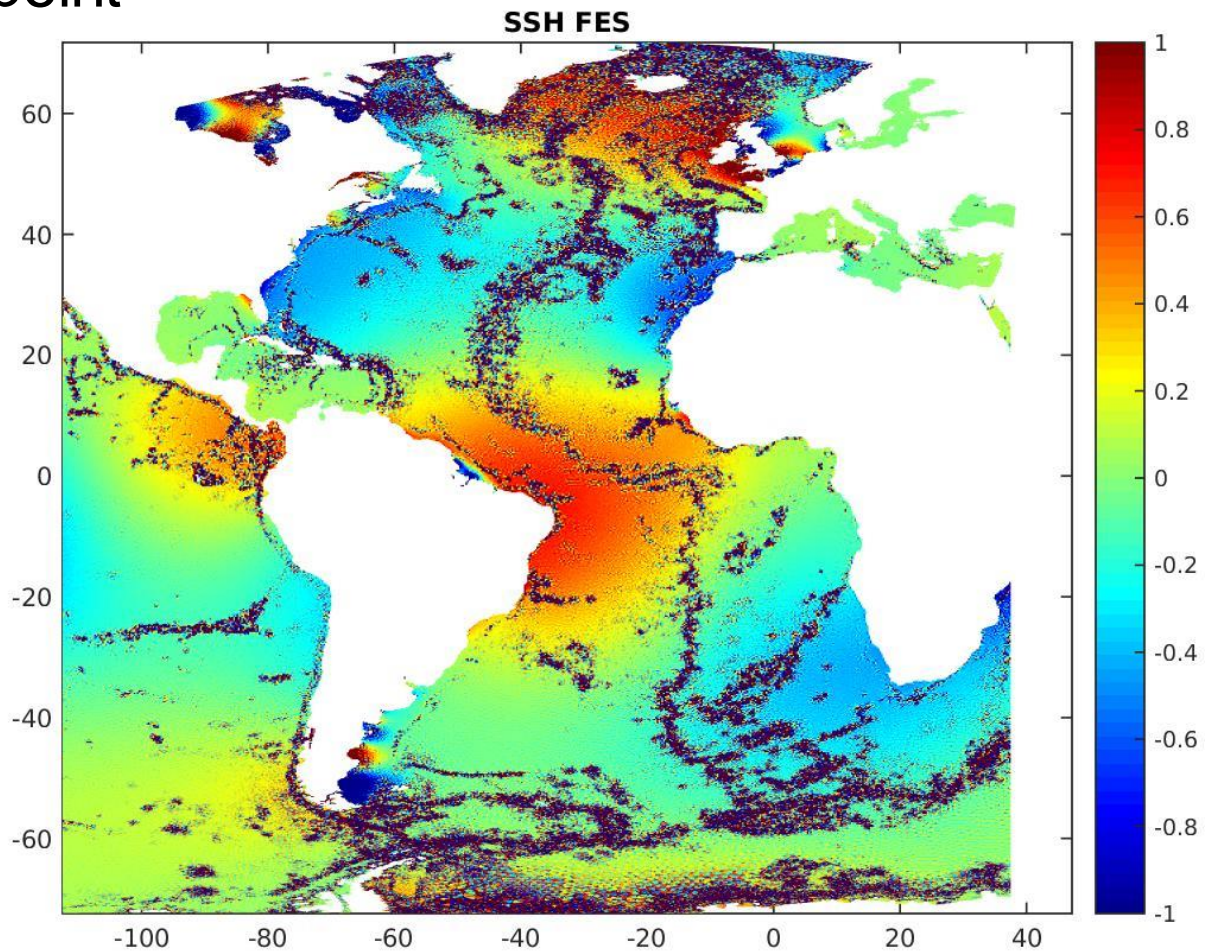
$$V = \text{Transport/Depth(NEMO)}$$



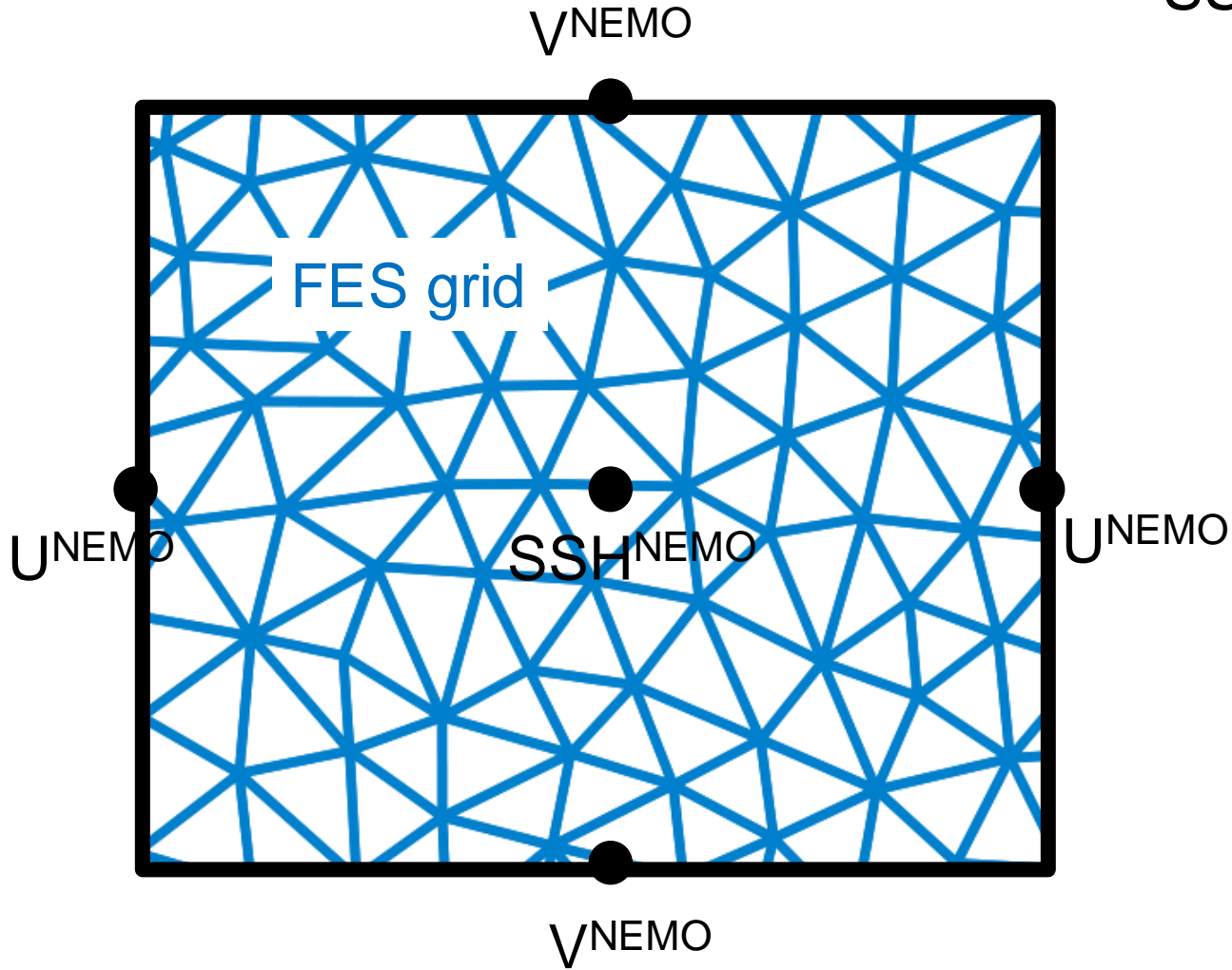
# Results with real FES fields

FES Solution interpolated  
On single NEMO grid point

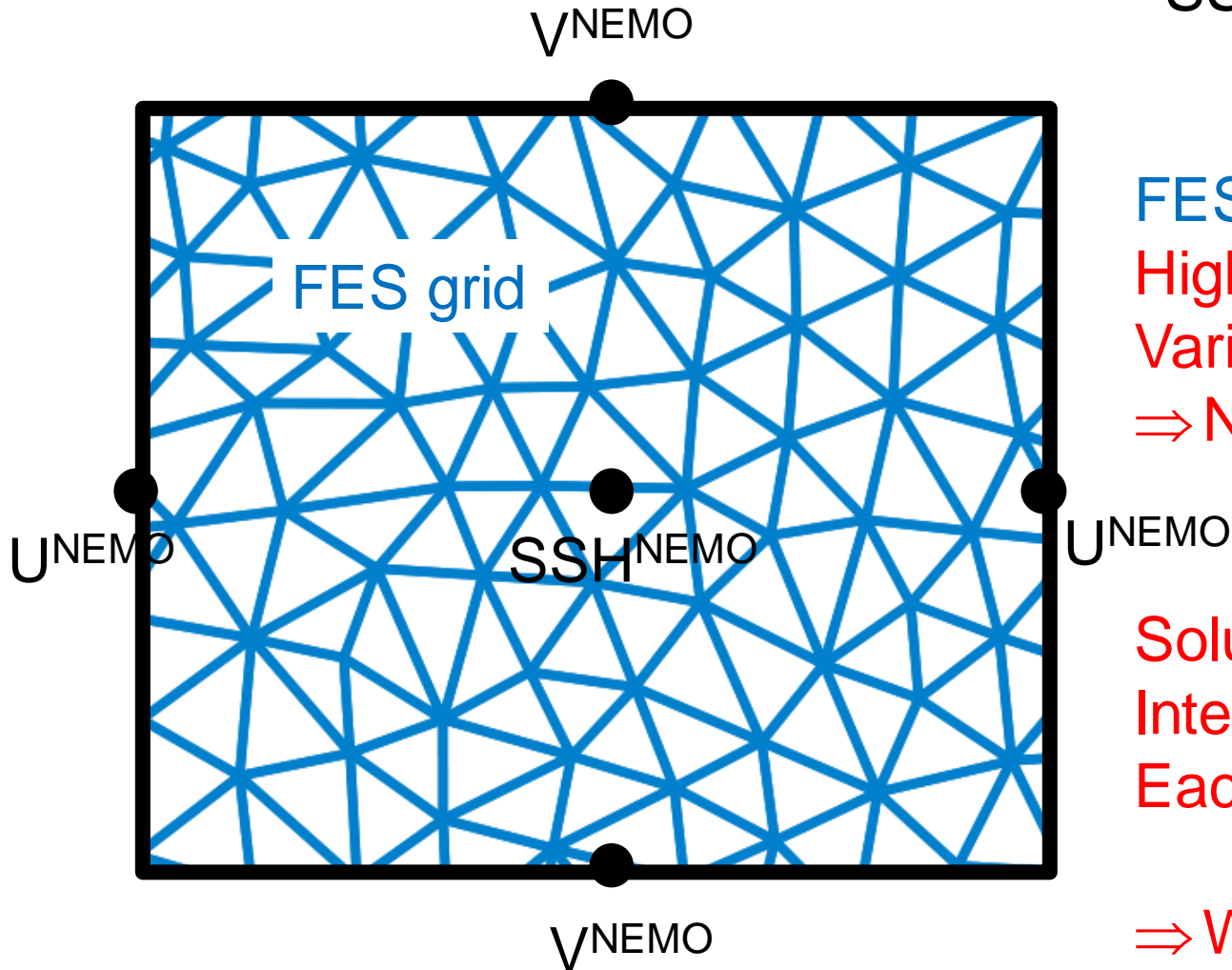
$$SSH = \text{div}(\text{Transport})$$



$$\text{SSH}^{\text{NEMO}} = \text{div } \mathbf{U}^{\text{NEMO}}$$



$$SSH^{NEMO} = \text{div } U^{NEMO}$$



FES grid

High resolution / topo  
Variability

⇒ Noise on NEMO grid

Solution :

Integrate FES fluxes along  
Each NEMO grid cell side

⇒ Warrantees that  
 $SSH^{NEMO} = \text{mean}(SSH^{FES})$



# CONCLUSION

## Properties / advantages

The solution of the circulation model is the projected FES solution=reference

The cost is equivalent or even cheaper than a "normal" model (it is a simple coding of a forcing term which can be calculated once and for all for each harmonic component)

Time filtering is not required (to treat the bottom friction for instance)

Implementation of method validated (automatically adapts to num schemes)

## Potential problems / disadvantage

-Implementation to finalize: currently difficulties with interpolation of FES solution on NEMO grid, but we think we know how to do ...

-Other problems at poles (Achillee's heel of tide models)

- Non-linear term to look at (problem of rectification of the tide: a priori to be generated with the circulation model, but to be studied)

- If data assimilation used in FES (tide) model => equilibrium  $SSH = \text{div}(\text{Transport})$  to be ensured ...

