



Nucleus for European Modelling of the Ocean



Tracers in Ocean Paradigm (TOP) The NEMO passive tracers engine

Version 4.0.1 - October, 2019

Abstract

“Tracers in Ocean Paradigm” (*TOP*) is the passive tracers engine of the *NEMO* ocean model (“Nucleus for European Modelling of the Ocean”). It is intended to be a flexible tool for studying the on/offline oceanic tracers transport and the biogeochemical processes (“green ocean”), as well as its interactions with the other components of the Earth climate system over a wide range of space and time scales. *TOP* is interfaced with the *NEMO* ocean engine, and, via the *OASIS* coupler, with several atmospheric general circulation models.

This component provides the physical constraints and boundaries conditions for oceanic tracers transport and represents a generalized, hardwired interface toward biogeochemical models to enable a seamless coupling. In particular, transport dynamics are supplied by the ocean dynamical core thus enabling the use of all available advection and diffusion schemes in both on- and off-line modes. *TOP* is designed to handle multiple oceanic tracers through a modular approach and it includes different sub-modules: ocean water age, inorganic carbon (CFCs) & radiocarbon (C14b), built-in biogeochemical model (PISCES), and prototype for user-defined cases or coupling with alternative biogeochemical models (*e.g.* *BFM*).

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Community

Ocean

Model

Disclaimer

Like all components of the modelling framework, the TOP core engine is developed under the [CECILL license](#), which is a French adaptation of the GNU GPL (General Public License). Anyone may use it freely for research purposes, and is encouraged to communicate back to the development team its own developments and improvements.

The model and the present document have been made available as a service to the community. We cannot certify that the code and its manual are free of errors. Bugs are inevitable and some have undoubtedly survived the testing phase. Users are encouraged to bring them to our attention.

The authors assume no responsibility for problems, errors, or incorrect usage of *NEMO*.

Other resources

Additional information can be found on:

- [W](#) the [website](#) of the project detailing several associated applications and an exhaustive users bibliography
- [P](#) the [development platform](#) of the model with the code repository for the shared reference and some main resources (wiki, ticket system, forums, . . .)
- [R](#) the [repository of the demonstration cases](#) for research or training
- [A](#) the [online archive](#) delivering the publications issued by the consortium (manuals, reports, datasets, . . .)
- [M](#) two mailing lists: the [newsletter](#) for top-down communications from the project (announcements, calls, job opportunities, . . .) and the [forge updates](#) (commits, tickets and forums)

Citation

Reference for papers and other publications is as follows:

“**Tracers in Ocean Paradigm (TOP)** – The NEMO passive tracers engine”, *Scientific Notes of Climate Modelling Center*, **28** — ISSN 1288-1619, Institut Pierre-Simon Laplace (IPSL), [doi:10.5281/zenodo.1471700](#)

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TOP (Tracers in the Ocean Paradigm) handles oceanic passive tracers in NEMO. At present, this component provides the physical constraints and boundary conditions for oceanic tracers transport and represents a generalized, hardwired interface toward biogeochemical models to enable a seamless coupling.

It includes three independent components :

- a transport code TRP sharing the same advection/diffusion routines with the dynamics, with specific treatment of some features like the surface boundary conditions, or the positivity of passive tracers concentrations
- sources and sinks - SMS - models that can be typically biogeochemical, biological or radioactive
- an offline option which is a simplified OPA 9 model using fields of physics variables that are previously stored to disk

There is two ways of coupling TOP to the dynamics :

- *online coupling* : the evolution of passive tracers is computed along with the dynamics
- *offline coupling* : the fields of physics variables are read from files and interpolated at each model time step, with no constraints on the time sampling in the input files

TOP is designed to handle multiple oceanic tracers through a modular approach and it includes different sub-modules :

- the ocean water age module (AGE) tracks down the time-dependent spread of surface waters into the ocean interior
- inorganic carbon (e.g. CFCs, SF6) and radiocarbon (C14) passive tracers can be modeled to assess ocean absorption timescales of anthropogenic emissions and further address water masses ventilation
- a built-in biogeochemical model (PISCES) to simulate lower trophic levels ecosystem dynamics in the global ocean
- a prototype tracer module (MY_TRC) to enable user-defined cases or the coupling with alternative biogeochemical models (e.g. BFM, MEDUSA, ERSEM, BFM, ECO3M)

TOP : Tracers in the Ocean Paradigm

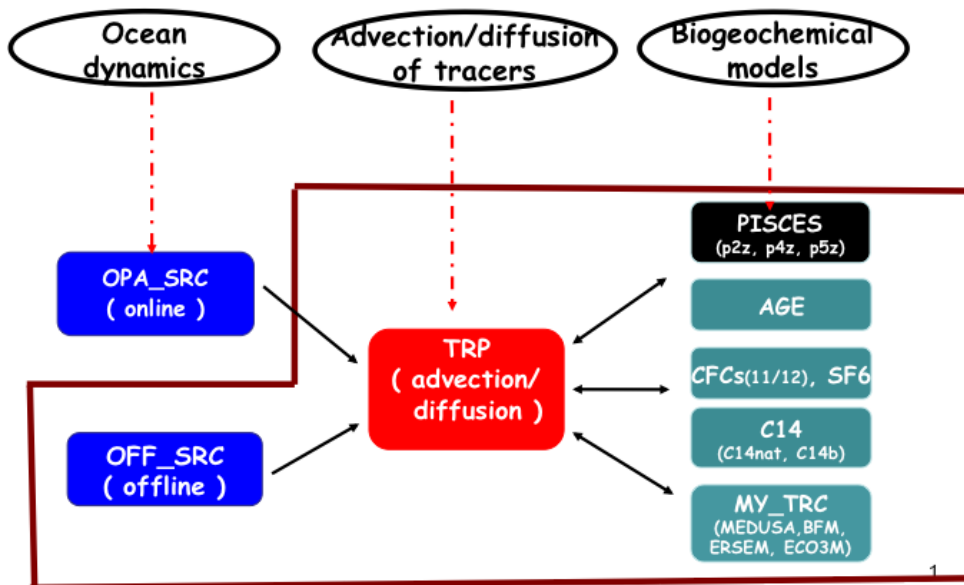


Figure 0.1.: A schematic view of NEMO-TOP component

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1.1. Basics

The time evolution of any passive tracer C follows the transport equation, which is similar to that of active tracer - temperature or salinity :

$$\frac{\partial C}{\partial t} = S(C) - \frac{1}{b_t} \left[\frac{\partial e_{2u} e_{3u} u C}{\partial i} + \frac{\partial e_{1v} e_{3v} uv, C}{\partial i} \right] + \frac{1}{e_{3t}} \frac{\partial w C}{\partial k} + D^{lC} + D^{vC} \quad (1.1)$$

where expressions of D^{lC} and D^{vC} depend on the choice for the lateral and vertical subgrid scale parameterizations, see equations 5.10 and 5.11 in (Gurvan and Team, TBD)

$S(C)$, the first term on the right hand side of 1.1; is the SMS - Source Minus Sink - inherent to the tracer. In the case of biological tracer such as phytoplankton, $S(C)$ is the balance between phytoplankton growth and its decay through mortality and grazing. In the case of a tracer comprising carbon, $S(C)$ accounts for gas exchange, river discharge, flux to the sediments, gravitational sinking and other biological processes. In the case of a radioactive tracer, $S(C)$ is simply loss due to radioactive decay.

The second term (within brackets) represents the advection of the tracer in the three directions. It can be interpreted as the budget between the incoming and outgoing tracer fluxes in a volume T -cells $b_t = e_{1t} e_{2t} e_{3t}$

The third term represents the change due to lateral diffusion.

The fourth term is change due to vertical diffusion, parameterized as eddy diffusion to represent vertical turbulent fluxes :

$$D^{vC} = \frac{1}{e_{3t}} \frac{\partial}{\partial k} \left[A^{vT} \frac{\partial C}{\partial k} \right] \quad (1.2)$$

where A^{vT} is the vertical eddy diffusivity coefficient of active tracers

1.2. The NEMO-TOP interface

TOP is the NEMO hardwired interface toward biogeochemical models and provide the physical constraints/boundaries for oceanic tracers. It consists of a modular framework to handle multiple ocean tracers, including also a variety of built-in modules.

This component of the NEMO framework allows one to exploit available modules and further develop a range of applications, spanning from the implementation of a dye passive tracer to evaluate dispersion processes (by means of MY_TRC), track water masses age (AGE module), assess the ocean interior penetration of persistent chemical compounds (e.g., gases like CFC or even PCBs), up to the full set of equations involving marine biogeochemical cycles.

TOP interface has the following location in the code repository : <repository>/src/TOP/
and the following modules are available:

- **TRP** : Interface to NEMO physical core for computing tracers transport
- **CFC** : Inert carbon tracers (CFC11,CFC12, SF6)
- **C14** : Radiocarbon passive tracer
- **AGE** : Water age tracking
- **MY_TRC** : Template for creation of new modules and external BGC models coupling
- **PISCES** : Built in BGC model. See (Aumont et al., 2015) for a throughout description.

1.3. The transport component : TRP

The passive tracer transport component shares the same advection/diffusion routines with the dynamics, with specific treatment of some features like the surface boundary conditions, or the positivity of passive tracers concentrations.

1.3.1. Advection

```

!-----
&namtrc_adv      !  advection scheme for passive tracer                (default: NO selection)
!-----
ln_trcadv_off   = .false.  !  No passive tracer advection
ln_trcadv_cen   = .false.  !  2nd order centered scheme
  nn_cen_h      = 4         !  =2/4, horizontal 2nd order CEN / 4th order CEN
  nn_cen_v      = 4         !  =2/4, vertical 2nd order CEN / 4th order COMPACT
ln_trcadv_fct   = .false.  !  FCT scheme
  nn_fct_h      = 2         !  =2/4, horizontal 2nd / 4th order
  nn_fct_v      = 2         !  =2/4, vertical 2nd / COMPACT 4th order
ln_trcadv_mus   = .false.  !  MUSCL scheme
  ln_mus_ups    = .false.  !  use upstream scheme near river mouths
ln_trcadv_ubs   = .false.  !  UBS scheme
  nn_ubs_v      = 2         !  =2 , vertical 2nd order FCT
ln_trcadv_qck   = .false.  !  QUICKEST scheme
/

```

The advection schemes used for the passive tracers are the same than the ones for T and S and described in section 5.1 of (Gurvan and Team, TBD). The choice of an advection scheme can be selected independently and can differ from the ones used for active tracers. This choice is made in the *namtrc_adv* namelist, by setting to *true* one and only one of the logicals *ln_trcadv_XXX*, the same way of what is done for dynamics. *cen2*, *MUSCL2*, and *UBS* are not *positive* schemes meaning that negative values can appear in an initially strictly positive tracer field which is advected, implying that false extrema are permitted. Their use is not recommended on passive tracers

1.3.2. Lateral diffusion

```

!-----
&namtrc_ldf      !  lateral diffusion scheme for passive tracer        (default: NO selection)
!-----
!                                     !  Type of the operator:
ln_trcldf_off   = .false.  !  No explicit diffusion
ln_trcldf_tra   = .false.  !  use active tracer setting
!                                     !  Coefficient (defined with namtra_ldf coefficient)
rn_ldf_multi    = 1.       !  multiplier of aht for TRC mixing coefficient
rn_fact_lap     = 1.       !  Equatorial enhanced zonal eddy diffusivity (lap only)
/

```

In NEMO v4.0, the passive tracer diffusion has necessarily the same form as the active tracer diffusion, meaning that the numerical scheme must be the same. However the passive tracer mixing coefficient can be chosen as a multiple of the active ones by changing the value of `rn_ldf_multi` in namelist `namtrc_ldf`. The choice of numerical scheme is then set in the `&namnamtra_ldf` (??) namelist for the dynamic described in section 5.2 of (Gurvan and Team, TBD).

1.3.3. Tracer damping

```

!-----
&namtrc_dmp      ! passive tracer newtonian damping              (ln_trcdmp=T)
!-----
nn_zdmp_tr      = 1      ! vertical shape =0 damping throughout the water column
                  !                               =1 no damping in the mixing layer (kz criteria)
                  !                               =2 no damping in the mixed layer (rho criteria)
cn_resto_tr      = 'resto_tr.nc' ! create a damping.coeff NetCDF file (=1) or not (=0)
/

```

The use of newtonian damping to climatological fields or observations is also coded, sharing the same routine dans active tracers. Boolean variables are defined in the namelist `top_ref` to select the tracers on which restoring is applied. Options are defined through the `&namnamtrc_dmp` (??) namelist variables. The restoring term is added when the namelist parameter `ln_trcdmp` is set to true. The restoring coefficient is a three-dimensional array read in a file, which name is specified by the namelist variable `cn_resto_tr`. This netcdf file can be generated using the DMP_TOOLS tool.

1.3.4. Tracer positivity

```

!-----
&namtrc_rad      ! treatment of negative concentrations
!-----
ln_trcrad        = .true.  ! artificially correct negative concentrations (T) or not (F)
/

```

Sometimes, numerical scheme can generates negative values of passive tracers concentration that must be positive. For exemple, isopycnal diffusion can created extrema. The `trcrad` routine artificially corrects negative concentrations with a very crude solution that either sets negative concentration to zero without adjusting the tracer budget, or by removing negative concentration and keeping mass conservation. The treatment of negative concentrations is an option and can be selected in the namelist `&namnamtrc_rad` (??) by setting the parameter `ln_trcrad` to true.

1.4. The SMS modules

1.4.1. Ideal Age

```

!-----
&namage          ! AGE
!-----
rn_age_depth      = 10      ! depth over which age tracer reset to zero
rn_age_kill_rate  = -0.000138888 ! = -1/7200 recip of relaxation timescale (s) for age tracer shallower
                    ↳ than age_depth
/

```

An ‘ideal age’ tracer is integrated online in TOP when `ln_age = .true.` in namelist `namtrc`. This tracer marks the length of time in units of years that fluid has spent in the interior of the ocean, insulated from exposure to the atmosphere. Thus, away from the surface for $z < -H_{\text{Age}}$ where H_{Age} is specified by the `namage` namelist variable `rn_age_depth`, whose default value is 10 m, there is a source SMS_{Age} of the age tracer A :

$$\text{SMS}_{\text{Age}} = 1\text{yr}^{-1} = 1/T_{\text{year}}, \quad (1.3)$$

where the length of the current year $T_{\text{year}} = 86400 * N_{\text{days in current year}}$ s, where $N_{\text{days in current year}}$ may be 366 or 365 depending on whether the current year is a leap year or not. Near the surface, for $z > -H_{\text{Age}}$, ideal age is relaxed back to zero:

$$\text{SMS}_{\text{Age}} = -\lambda_{\text{Age}}A, \quad (1.4)$$

where the relaxation rate λ_{Age} (units s^{-1}) is specified by the *namage* namelist variable *rn_age_kill_rate* and has a default value of $1/7200$ s. Since this relaxation is applied explicitly, this relaxation rate in principle should not exceed $1/\Delta t$, where Δt is the time step used to step forward passive tracers ($2 * nm_dttrc * rn_rdt$ when the default leapfrog time-stepping scheme is employed).

Currently the 1-dimensional reference depth of the grid boxes is used rather than the dynamically evolving depth to determine whether the age tracer is incremented or relaxed to zero. This means that the tracer only works correctly in *z*-coordinates. To ensure that the forcing is independent of the level thicknesses, where the tracer cell at level *k* has its upper face $z = -depw(k)$ above the depth $-H_{\text{Age}}$, but its lower face $z = -depw(k+1)$ below that depth, then the age source

$$\text{SMS}_{\text{Age}} = -f_{\text{kill}}\lambda_{\text{Age}}A + f_{\text{add}}/T_{\text{year}}, \quad (1.5)$$

where

$$f_{\text{kill}} = e3t_k^{-1}(H_{\text{Age}} - depw(k)), \quad (1.6)$$

$$f_{\text{add}} = 1 - f_{\text{kill}}. \quad (1.7)$$

This implementation was first used in the CORE-II intercomparison runs described e.g. in [Danabasoglu et al. \(2014\)](#).

1.4.2. Inert carbons tracer

```
!-----
&namcfc      !   CFC
!-----
!
  ndate_beg   = 300101   !   datedebl
  nyear_res   = 1932     !   ianneel
!
! Formatted file of annual hemispheric CFCs concentration in the atmosphere (ppt)
  clname      = 'CFCs_CDIAc.dat'
/
```

Chlorofluorocarbons 11 and 12 (CFC-11 and CFC-12), and sulfur hexafluoride (SF₆), are synthetic chemicals manufactured for industrial and domestic applications from the early 20th century onwards. CFC-11 (CCl₃F) is a volatile liquid at room temperature, and was widely used in refrigeration. CFC-12 (CCl₂F₂) is a gas at room temperature, and, like CFC-11, was widely used as a refrigerant, and additionally as an aerosol propellant. SF₆ (SF₆) is also a gas at room temperature, with a range of applications based around its property as an excellent electrical insulator (often replacing more toxic alternatives). All three are relatively inert chemicals that are both non-toxic and non-flammable, and their wide use has led to their accumulation within the Earth's atmosphere. Large-scale production of CFC-11 and CFC-12 began in the 1930s, while production of SF₆ began in the 1950s, and their atmospheric concentration time-histories are shown in [Figure 1.1](#). As can be seen in the figure, while the concentration of SF₆ continues to rise to the present day, the concentrations of both CFC-11 and CFC-12 have levelled off and declined since around the 1990s. These declines have been driven by the Montreal Protocol (effective since August 1989), which has banned the production of CFC-11 and CFC-12 (as well as other CFCs) because of their role in the depletion of stratospheric ozone (O₃), critical in decreasing the flux of ultraviolet radiation to the Earth's surface. Separate to this role in ozone-depletion, all three chemicals are significantly more potent greenhouse gases than CO₂ (especially SF₆), although their relatively low atmospheric concentrations limit their role in climate change.

The ocean is a notable sink for all three gases, and their relatively recent occurrence in the atmosphere, coupled to the ease of making high precision measurements of their dissolved concentrations, has made them valuable in oceanography. Because they only enter the ocean via surface air-sea exchange, and are almost completely chemically and biologically inert, their distribution within the ocean interior reveals its ventilation via transport and mixing. Measuring the dissolved concentrations of the gases – as well as the mixing ratios between them – shows circulation pathways within the ocean as well as water mass ages (i.e. the time since last contact with the atmosphere). This feature of the gases has made them valuable across a wide range of oceanographic problems. One use lies in ocean modelling, where they can be used to evaluate the realism of the circulation and ventilation of models, key for understanding the behaviour of wider modelled marine biogeochemistry (e.g. [Dutay et al., 2002](#); [Palmiéri et al., 2015](#)).

Modelling these gases (henceforth CFCs) in NEMO is done within the passive tracer transport module, TOP, using the conservation state equation [1.1](#)

Advection and diffusion of the CFCs in NEMO are calculated by the physical module, OPA, whereas sources and sinks are done by the CFC module within TOP. The only source for CFCs in the ocean is via air-sea gas exchange at its surface, and since CFCs are generally stable within the ocean, we assume that there are no sinks (i.e. no loss processes) within the ocean interior. Consequently, the sinks-minus-sources term for CFCs consists only of their air-sea fluxes, F_{cfc} , as described in the Ocean Model Inter-comparison Project (OMIP) protocol ([Orr et al., 2017](#)):

$$F_{cfc} = K_w \cdot (C_{sat} - C_{surf}) \cdot (1 - f_i) \quad (1.8)$$

Where K_w is the piston velocity (in m s^{-1}), as defined in Equation 1.10; C_{sat} is the saturation concentration of the CFC tracer, as defined in Equation 1.9; C_{surf} is the local surface concentration of the CFC tracer within the model (in mol m^{-3}); and f_i is the fractional sea-ice cover of the local ocean (ranging between 0.0 for ice-free ocean, through to 1.0 for completely ice-covered ocean with no air-sea exchange).

The saturation concentration of the CFC, C_{sat} , is calculated as follows:

$$C_{sat} = Sol \cdot P_{cfc} \quad (1.9)$$

Where Sol is the gas solubility in $\text{mol m}^{-3} \text{pptv}^{-1}$, as defined in Equation 1.12; and P_{cfc} is the atmosphere concentration of the CFC (in parts per trillion by volume, pptv). This latter concentration is provided to the model by the historical time-series of Bullister (2017). This includes bulk atmospheric concentrations of the CFCs for both hemispheres – this is necessary because of the geographical asymmetry in the production and release of CFCs to the atmosphere. Within the model, hemispheric concentrations are uniform, with the exception of the region between 10°N and 10° in which they are linearly interpolated.

The piston velocity K_w is a function of 10 m wind speed (in m s^{-1}) and sea surface temperature, T (in $^\circ\text{C}$), and is calculated here following Wanninkhof (1992):

$$K_w = X_{conv} \cdot a \cdot u^2 \cdot \sqrt{\frac{Sc(T)}{660}} \quad (1.10)$$

Where $X_{conv} = \frac{0.01}{3600}$, a conversion factor that changes the piston velocity from cm h^{-1} to m s^{-1} ; a is a constant re-estimated by Wanninkhof (2014) to 0.251 (in $\frac{\text{cm h}^{-1}}{(\text{m s}^{-1})^2}$); and u is the 10 m wind speed in m s^{-1} from either an atmosphere model or reanalysis atmospheric forcing. Sc is the Schmidt number, and is calculated as follow, using coefficients from Wanninkhof (2014) (see Table 1.2).

$$Sc = a0 + (a1 \cdot T) + (a2 \cdot T^2) + (a3 \cdot T^3) + (a4 \cdot T^4) \quad (1.11)$$

The solubility, Sol , used in Equation 1.9 is calculated in $\text{mol l}^{-1} \text{atm}^{-1}$, and is specific for each gas. It has been experimentally estimated by Warner and Weiss (1985) as a function of temperature and salinity:

$$\ln(Sol) = a_1 + \frac{a_2}{T_X} + a_3 \cdot \ln T_X + a_4 \cdot T_X^2 + S \cdot (b_1 + b_2 \cdot T_X + b_3 \cdot T_X^2) \quad (1.12)$$

Where T_X is $\frac{T+273.16}{100}$, a function of temperature; and the a_x and b_x coefficients are specific for each gas (see Table 1.1). This is then converted to $\text{mol m}^{-3} \text{pptv}^{-1}$ assuming a constant atmospheric surface pressure of 1 atm. The solubility of CFCs thus decreases with rising T while being relatively insensitive to salinity changes. Consequently, this translates to a pattern of solubility where it is greatest in cold, polar regions (see Figure 1.2).

The standard outputs of the CFC module are seawater CFC concentrations (in mol m^{-3}), the net air-sea flux (in $\text{mol m}^{-2} \text{d}^{-1}$) and the cumulative net air-sea flux (in mol m^{-2}). Using XIOS, it is possible to obtain outputs such as the vertical integral of CFC concentrations (in mol m^{-2} ; see Figure 1.3). This property, when divided by the surface CFC concentration, estimates the local penetration depth (in m) of the CFC.

Notes

In comparison to the OMIP protocol, the CFC module in NEMO has several differences:

For instance, C_{sat} is calculated for a fixed surface pressure of 1atm, what could be corrected in a further version of the module.

1.4.3. Radiocarbon

```

!-----
&namcl4_fcg      ! files & dates
!               ! For Paleo-historical: specify tyrc14_beg in yr BP
!               ! For Bomb: tyrc14_beg=0
!-----
cfileco2        = 'splco2.dat' ! atmospheric co2 - Bomb

```

Table 1.1.: Coefficients for fit of the CFCs solubility (Eq. 1.12).

Gas	a1	a2	a3	a4	b1	b2	b3
CFC-11	-218.0971	298.9702	113.8049	-1.39165	-0.143566	0.091015	-0.0153924
CFC-12	-229.9261	319.6552	119.4471	-1.39165	-0.142382	0.091459	-0.0157274
SF6	-80.0343	117.232	29.5817	0.0	0.0335183	-0.0373942	0.00774862

Table 1.2.: Coefficients for fit of the CFCs Schmidt number (Eq. 1.11).

Gas	a0	a1	a2	a3	a4
CFC-11	3579.2	-222.63	7.5749	-0.14595	0.0011874
CFC-12	3828.1	-249.86	8.7603	-0.1716	0.001408
SF6	3177.5	-200.57	6.8865	-0.13335	0.0010877

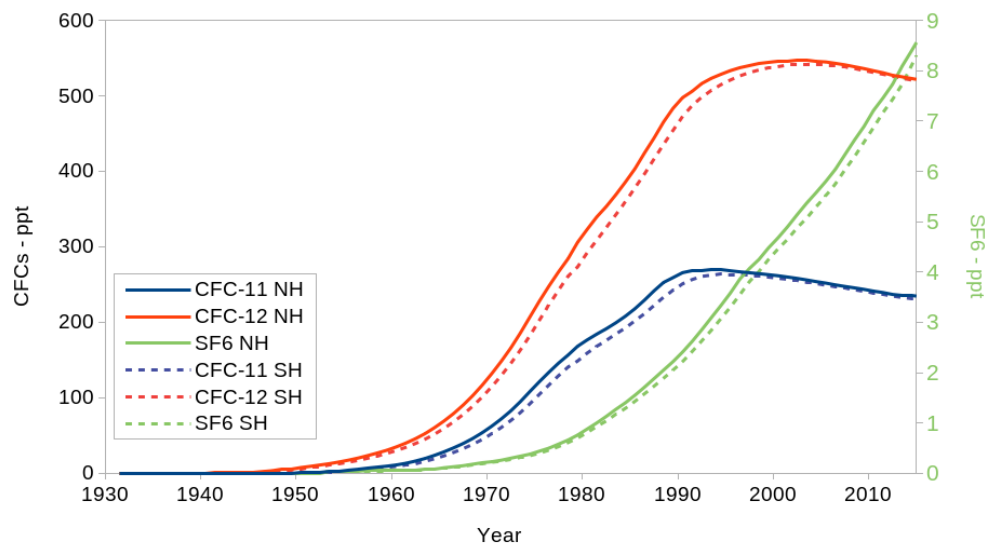
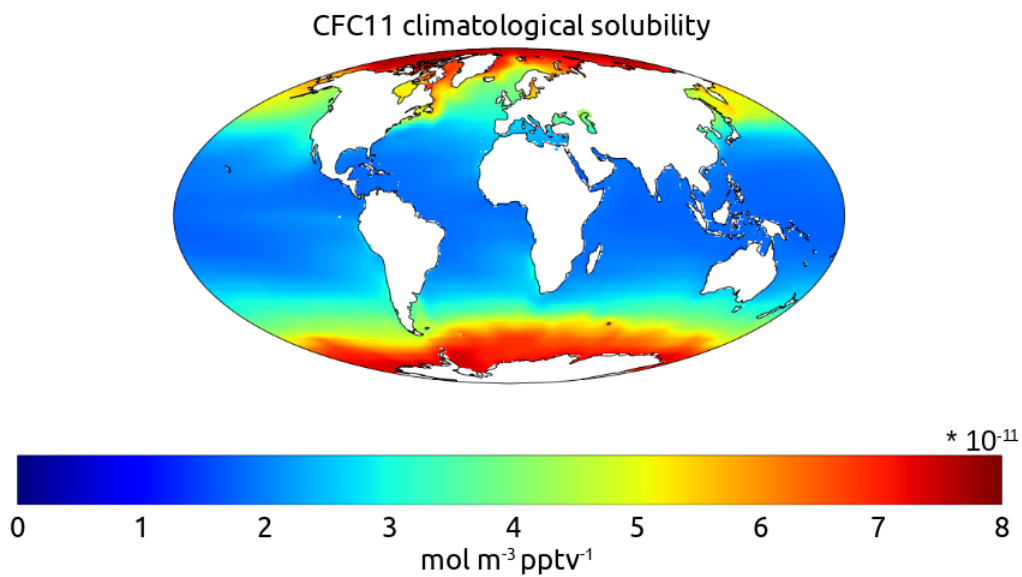


Figure 1.1.: Atmospheric CFC11, CFC12 and SF6 partial pressure evolution in both hemispheres.

Figure 1.2.: CFC11 solubility in mol m⁻³ pptv⁻¹, calculated from the World Ocean Atlas 2013 temperature and salinity annual climatology.

```

cfilec14 = 'atmc14.dat' ! atmospheric c14 - Bomb
tyrc14_beg = 0.00 ! starting year of experiment - Bomb
! cfileco2 = 'ByrdEdcCO2.txt' ! atmospheric co2 - Paleo

```

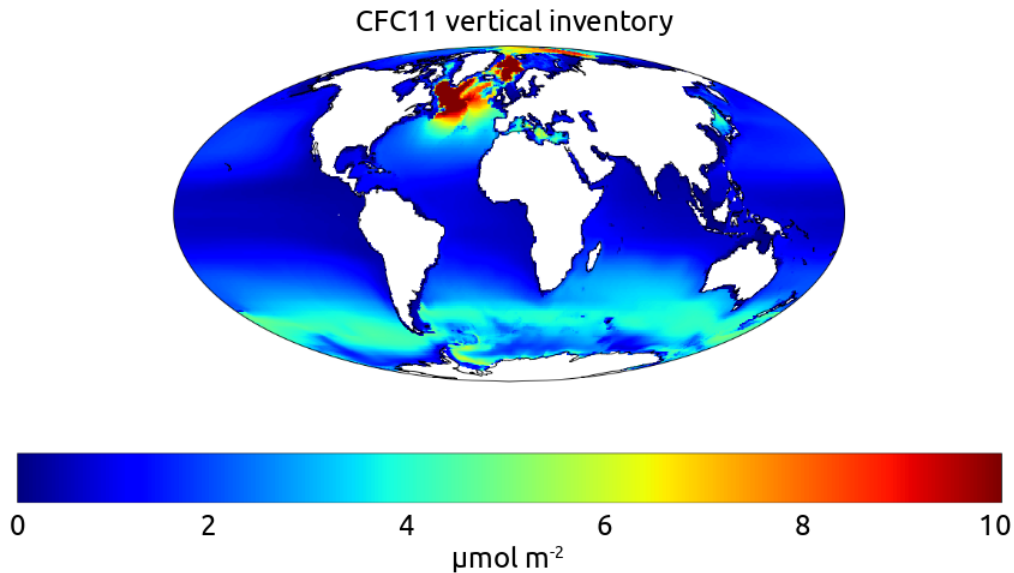


Figure 1.3.: CFC11 vertical inventory in $\mu\text{mol m}^{-2}$, from one of the UK Earth System Model 1 model (UKESM1 - which uses NEMO as ocean component, with TOP for the passive tracers) historical run at year 2000.

```
! cfilec14 = 'intcall13.14c' ! atmospheric c14 - Paleo
! tyrc14_beg = 35000.00 ! starting year of experiment - Paleo (yr BP)
/
```

```
!-----
&namc14_typ ! C14 - type of C14 tracer, default values of C14/C and pco2
!-----
kc14typ = 0 ! Type of C14 tracer (0=equilibrium; 1=bomb transient; 2=past transient)
rc14at = 1.0 ! Default value for atmospheric C14/C (used for equil run)
pco2at = 280.0 ! Default value for atmospheric pco2 [atm] (used for equil run)
rc14init = 0.85 ! Default value for initialization of ocean C14/C (when no restart)
/
```

```
!-----
&namc14_sbc ! C14 - surface BC
!-----
ln_chemh = .true. ! Chemical enhancement in piston vel.: yes/no
xkwind = 0.360 ! Coefficient for gas exchange velocity
xdicsur = 2.0 ! Reference DIC surface concentration (mol/m3)
/
```

The C14 package implemented in NEMO by Anne Mouchet models ocean $\Delta^{14}\text{C}$. It offers several possibilities: $\Delta^{14}\text{C}$ as a physical tracer of the ocean ventilation (natural ^{14}C), assessment of bomb radiocarbon uptake, as well as transient studies of paleo-historical ocean radiocarbon distributions.

Method

Let ^{14}R represent the ratio of ^{14}C atoms to the total number of carbon atoms in the sample, i.e. $^{14}\text{C}/\text{C}$. Then, radiocarbon anomalies are reported as

$$\Delta^{14}\text{C} = \left(\frac{^{14}\text{R}}{^{14}\text{R}_{\text{ref}}} - 1 \right) 10^3, \quad (1.13)$$

where $^{14}\text{R}_{\text{ref}}$ is a reference ratio. For the purpose of ocean ventilation studies $^{14}\text{R}_{\text{ref}}$ is set to one.

Here we adopt the approach of [Fiadeiro \(1982\)](#) and [Toggweiler et al. \(1989a,b\)](#) in which the ratio ^{14}R is transported rather than the individual concentrations C and ^{14}C . This approach calls for a strong assumption, i.e., that of a homogeneous and constant dissolved inorganic carbon (DIC) field ([Toggweiler et al., 1989a](#); [Mouchet, 2013](#)). While in terms of oceanic $\Delta^{14}\text{C}$, it yields similar results to approaches involving carbonate chemistry, it underestimates the bomb radiocarbon inventory because it assumes a constant air-sea CO_2 disequilibrium ([Mouchet, 2013](#)). Yet, field reconstructions of the ocean bomb ^{14}C inventory are also biased low ([Naegler, 2009](#)) since they assume that the anthropogenic perturbation

did not affect ocean DIC since the pre-bomb epoch. For these reasons, bomb ^{14}C inventories obtained with the present method are directly comparable to reconstructions based on field measurements.

This simplified approach also neglects the effects of fractionation (e.g., air-sea exchange) and of biological processes. Previous studies by [Bacastow and Maier-Reimer \(1990\)](#) and [Joos et al. \(1997\)](#) resulted in nearly identical $\Delta^{14}\text{C}$ distributions among experiments considering biology or not. Since observed ^{14}R ratios are corrected for the isotopic fractionation when converted to the standard $\Delta^{14}\text{C}$ notation ([Stuiver and Polach, 1977](#)) the model results are directly comparable to observations.

Therefore the simplified approach is justified for the purpose of assessing the circulation and ventilation of OGCMs.

The equation governing the transport of ^{14}R in the ocean is

$$\frac{\partial}{\partial t} {}^{14}\text{R} = -\nabla \cdot (\mathbf{u} {}^{14}\text{R} - \mathbf{K} \cdot \nabla {}^{14}\text{R}) - \lambda {}^{14}\text{R}, \quad (1.14)$$

where λ is the radiocarbon decay rate, \mathbf{u} the 3-D velocity field, and \mathbf{K} the diffusivity tensor.

At the air-sea interface a Robin boundary condition ([Haine, 2006](#)) is applied to (1.14), i.e., the flux through the interface is proportional to the difference in the ratios between the ocean and the atmosphere

$$\mathcal{F} = \kappa_R ({}^{14}\text{R} - {}^{14}\text{R}_a), \quad (1.15)$$

where \mathcal{F} is the flux out of the ocean, and ${}^{14}\text{R}_a$ is the atmospheric $^{14}\text{C}/\text{C}$ ratio. The transfer velocity κ_R for the radiocarbon ratio in (1.15) is computed as

$$\kappa_R = \frac{\kappa_{\text{CO}_2} K_0}{\overline{\text{C}}_T} p_{\text{CO}_2}^a \quad (1.16)$$

with κ_{CO_2} the carbon dioxide transfer or piston velocity, K_0 the CO_2 solubility in seawater, $p_{\text{CO}_2}^a$ the atmospheric CO_2 pressure at sea level, and $\overline{\text{C}}_T$ the average sea-surface dissolved inorganic carbon concentration.

The CO_2 transfer velocity is based on the empirical formulation of [Wanninkhof \(1992\)](#) with chemical enhancement ([Wanninkhof and Knox, 1996](#); [Wanninkhof, 2014](#)). The original formulation is modified to account for the reduction of the air-sea exchange rate in the presence of sea ice. Hence

$$\kappa_{\text{CO}_2} = (K_W w^2 + b) (1 - f_{\text{ice}}) \sqrt{660/S_c}, \quad (1.17)$$

with w the wind magnitude, f_{ice} the fractional ice cover, and S_c the Schmidt number. K_W in (1.17) is an empirical coefficient with dimension of an inverse velocity. The chemical enhancement term b is represented as a function of temperature T ([Wanninkhof, 1992](#))

$$b = 2.5(0.5246 + 0.016256T + 0.00049946 * T^2). \quad (1.18)$$

Model setup

To activate the C14 package, set the parameter `ln_c14 = .true.` in namelist `namtrc`.

Parameters and formulations The radiocarbon decay rate (RLAM14; in `trcnam_c14` module) is set to $\lambda = (1/8267) \text{ yr}^{-1}$ ([Stuiver and Polach, 1977](#)), which corresponds to a half-life of 5730 yr.

The Schmidt number S_c , Eq. (1.17), is calculated with the help of the formulation of [Wanninkhof \(2014\)](#). The CO_2 solubility K_0 in (1.16) is taken from [Weiss \(1974\)](#). K_0 and S_c are computed with the OGCM temperature and salinity fields (`trcsms_c14` module).

The following parameters intervening in the air-sea exchange rate are set in `namelist_c14`:

- The reference DIC concentration $\overline{\text{C}}_T$ (`XDICSUR`) intervening in (1.16) is classically set to 2 mol m^{-3} ([Toggweiler et al., 1989a](#); [Orr et al., 2001](#); [BUTZIN et al., 2005](#)).
- The value of the empirical coefficient K_W (`XKWIND`) in (1.17) depends on the wind field and on the model upper ocean mixing rate ([Toggweiler et al., 1989a](#); [Wanninkhof, 1992](#); [Naegler, 2009](#); [Wanninkhof, 2014](#)). It should be adjusted so that the globally averaged CO_2 piston velocity is $\kappa_{\text{CO}_2} = 16.5 \pm 3.2 \text{ cm/h}$ ([Naegler, 2009](#)).
- Chemical enhancement (term b in Eq. 1.18) may be set on/off by means of the logical variable `LN_CHEMH`.

Experiment type The type of experiment is determined by the value given to `kc14TYP` in `namelist_c14`. There are three possibilities:

1. natural $\Delta^{14}\text{C}$: `kc14TYP=0`
2. bomb $\Delta^{14}\text{C}$: `kc14TYP=1`

3. transient paleo-historical $\Delta^{14}\text{C}$: $\text{KC14TYP}=2$

Natural or Equilibrium radiocarbon $\text{KC14TYP}=0$

Unless otherwise specified in `namelist_c14`, the atmospheric $^{14}\text{R}_a$ (RC14AT) is set to one, the atmospheric CO_2 (PCO2AT) to 280 ppm, and the ocean ^{14}R is initialized with $\text{RC14INIT}=0.85$, i.e., $\Delta^{14}\text{C} = -150\text{‰}$ (typical for deep-ocean, Fig 6 in Key et al., 2004).

Equilibrium experiment should last until 98% of the ocean volume exhibit a drift of less than 0.001‰/year (Orr et al., 2000); this is usually achieved after few kyr (Fig. 1.4).

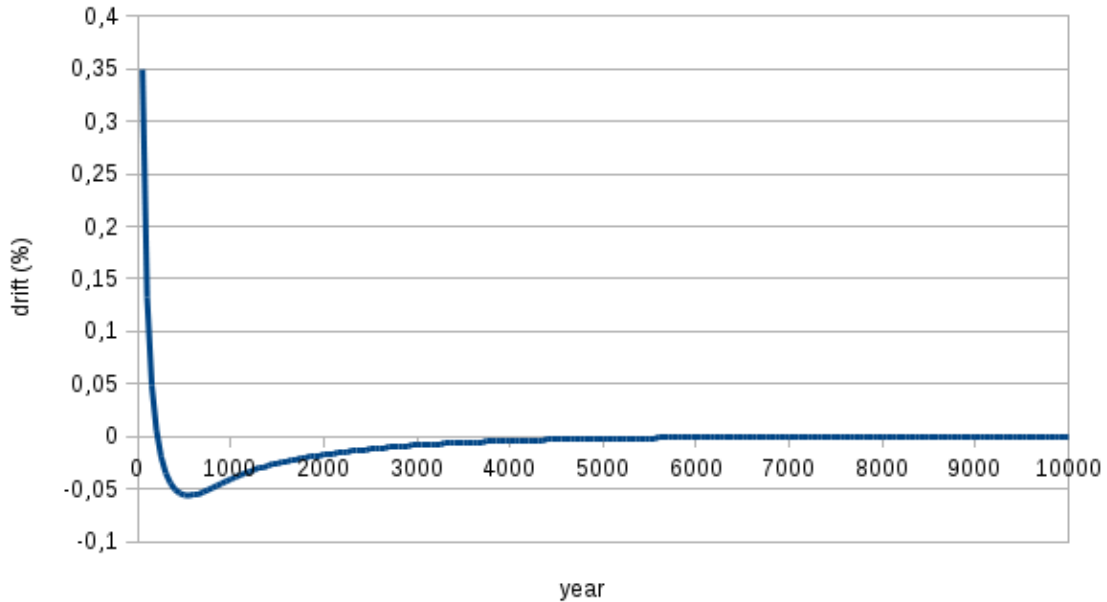


Figure 1.4.: Time evolution of ^{14}R inventory anomaly for equilibrium run with homogeneous ocean initial state. The anomaly (or drift) is given in % change in total ocean inventory per 50 years. Time on x-axis is in simulation year.

Transient: Bomb $\text{KC14TYP}=1$

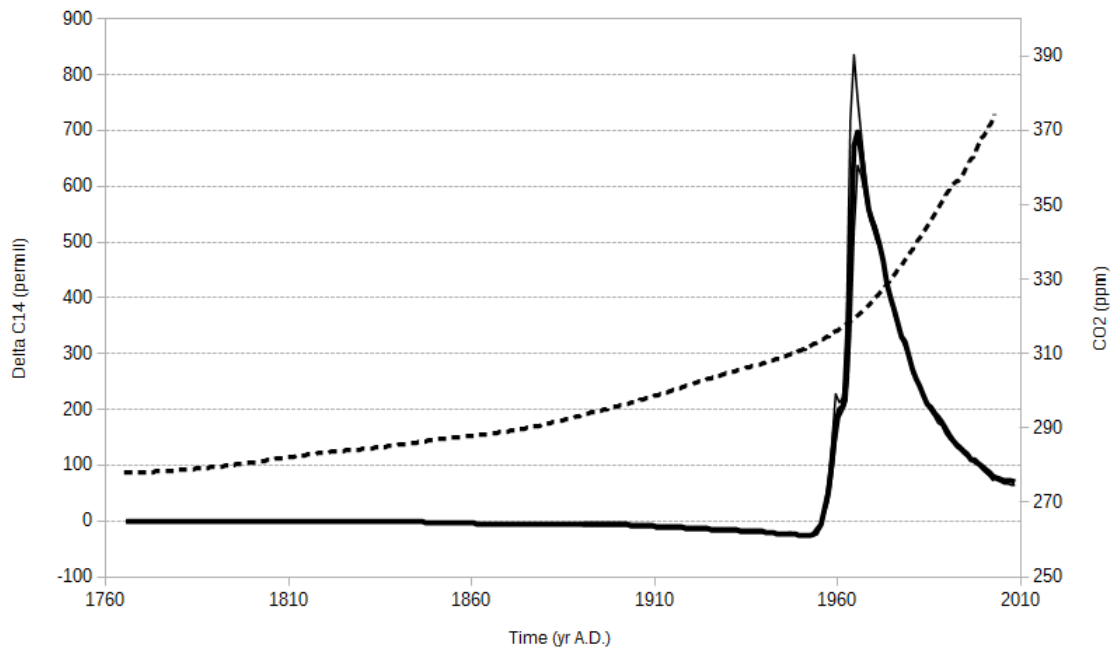


Figure 1.5.: Atmospheric $\Delta^{14}\text{C}$ (solid; left axis) and CO_2 (dashed; right axis) forcing for the ^{14}C -bomb experiments. The $\Delta^{14}\text{C}$ is illustrated for the three zonal bands (upper, middle, and lower curves correspond to latitudes $> 20\text{N}$, $\in [20\text{S}, 20\text{N}]$, and $< 20\text{S}$, respectively).

Performing this type of experiment requires that a pre-industrial equilibrium run be performed beforehand (`LN_RSTTR` should be set to `.TRUE.`).

An exception to this rule is when wishing to perform a perturbation bomb experiment as was possible with the package `C14b`. It is still possible to easily set-up that type of transient experiment for which no previous run is needed. In addition

to the instructions as given in this section it is however necessary to adapt the `atmc14.dat` file so that it does no longer contain any negative $\Delta^{14}\text{C}$ values (Suess effect in the pre-bomb period).

The model is integrated from a given initial date following the observed records provided from 1765 AD on (Fig. 1.5). The file `atmc14.dat` (G Enting et al., 1994, & I. Levin, personal comm.) provides atmospheric $\Delta^{14}\text{C}$ for three latitudinal bands: 90S-20S, 20S-20N & 20N-90N. Atmospheric CO_2 in the file `sp1co2.dat` is obtained from a spline fit through ice core data and direct atmospheric measurements (Orr et al., 2000, & J. Orr, personal comm.). Dates in these forcing files are expressed as yr AD.

To ensure that the atmospheric forcing is applied properly as well as that output files contain consistent dates and inventories the experiment should be set up carefully:

- Specify the starting date of the experiment: `NN_DATE0` in `namelist`. `NN_DATE0` is written as Year0101 where Year may take any positive value (AD).
- Then the parameters `NN_RSTCTL` in `namelist` (on-line) and `NN_RSTTR` in `namelist_top` (off-line) must be **set to 0** at the start of the experiment (force the date to `NN_DATE0` for the **first** experiment year).
- These two parameters (`NN_RSTCTL` and `NN_RSTTR`) have then to be **set to 2** for the following years (the date must be read in the restart file).

If the experiment date is outside the data time span then the first or last atmospheric concentrations are prescribed depending on whether the date is earlier or later. Note that `TYRC14_BEG` (`namelist_c14`) is not used in this context.

Transient: Past `KC14_TYP=2`

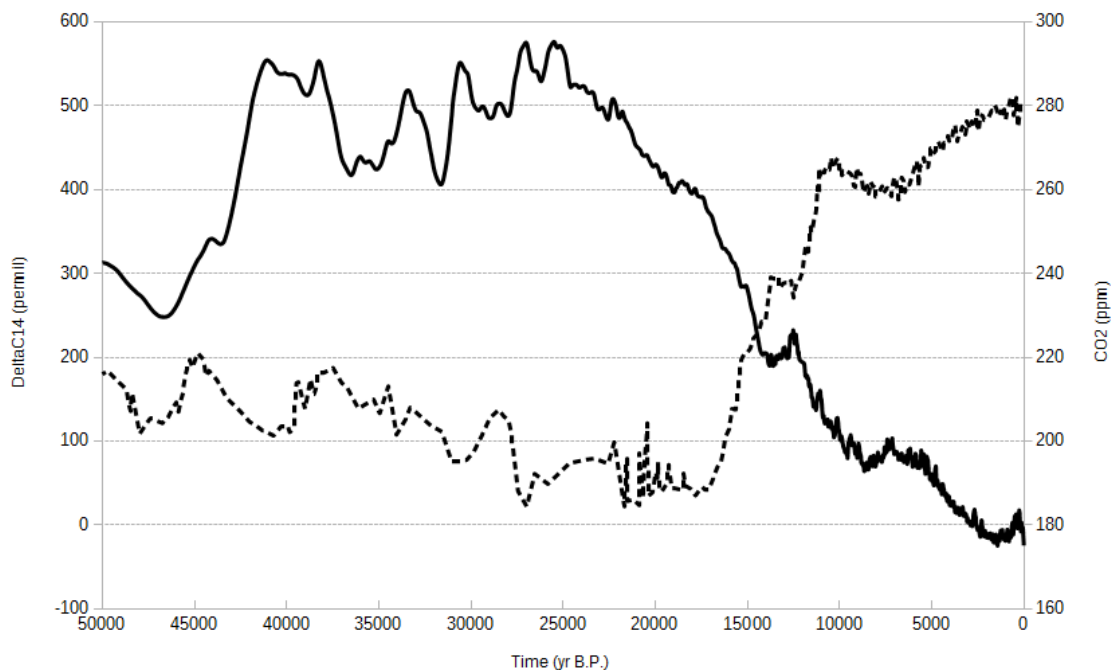


Figure 1.6.: Atmospheric $\Delta^{14}\text{C}$ (solid) and CO_2 (dashed) forcing for the Paleo experiments. The CO_2 scale is given on the right axis.

This experiment type does not need a previous equilibrium run. It should start 5–6 kyr earlier than the period to be analyzed. Atmospheric $^{14}\text{R}_a$ and CO_2 are prescribed from forcing files. The ocean ^{14}R is initialized with the value attributed to `RC14_INIT` in `namelist_c14`.

The file `intcal13.14c` (Reimer et al., 2013) contains atmospheric $\Delta^{14}\text{C}$ from 0 to 50 kyr cal BP*. The CO_2 forcing is provided in file `ByrdEdcCO2.txt`. The content of this file is based on the high resolution record from EPICA Dome C (Monnin et al., 2004) for the Holocene and the Transition, and on Byrd Ice Core CO_2 Data for 20–90 kyr BP (Ahn and Brook, 2008). These atmospheric values are reproduced in Fig. 1.6. Dates in these files are expressed as yr BP.

To ensure that the atmospheric forcing is applied properly as well as that output files contain consistent dates and inventories the experiment should be set up carefully. The true experiment starting date is given by `TYRC14_BEG` (in yr BP) in `namelist_c14`. In consequence, `NN_DATE0` in `namelist` MUST be set to 00010101.

Then the parameters `NN_RSTCTL` in `namelist` (on-line) and `NN_RSTTR` in `namelist_top` (off-line) must be set to 0 at the start of the experiment (force the date to `NN_DATE0` for the first experiment year). These two parameters have then to be set to 2 for the following years (read the date in the restart file).

If the experiment date is outside the data time span then the first or last atmospheric concentrations are prescribed depending on whether the date is earlier or later.

*cal BP: number of years before 1950 AD

Model output All output fields in Table 1.3 are routinely computed. It depends on the actual settings in `iodef.xml` whether they are stored or not.

Table 1.3.: Standard output fields for the C14 package .

Field	Type	Dim	Units	Description
RC14	ptrc	3-D	-	Radiocarbon ratio
DeltaC14	diad	3-D	‰	$\Delta^{14}\text{C}$
C14Age	diad	3-D	yr	Radiocarbon age
RAge	diad	2-D	yr	Reservoir age
qtr_c14	diad	2-D	$\text{m}^{-2} \text{yr}^{-1}$	Air-to-sea net ^{14}R flux
qint_c14	diad	2-D	m^{-2}	Cumulative air-to-sea ^{14}R flux
AtmCO2	scalar	0-D	ppm	Global atmospheric CO_2
AtmC14	scalar	0-D	‰	Global atmospheric $\Delta^{14}\text{C}$
K_CO2	scalar	0-D	cm h^{-1}	Global CO_2 piston velocity ($\overline{\kappa_{\text{CO}_2}}$)
K_C14	scalar	0-D	m yr^{-1}	Global ^{14}R transfer velocity ($\overline{\kappa_R}$)
C14Inv	scalar	0-D	10^{26} atoms	Ocean radiocarbon inventory

The radiocarbon age is computed as $(-1/\lambda) \ln(^{14}\text{R})$, with zero age corresponding to $^{14}\text{R} = 1$.

The reservoir age is the age difference between the ocean uppermost layer and the atmosphere. It is usually reported as conventional radiocarbon age; i.e., computed by means of the Libby radiocarbon mean life (8033 yr; [Stuiver and Polach, 1977](#))

$$^{14}\tau_c = -8033 \ln \left(1 + \frac{\Delta^{14}\text{C}}{10^3} \right), \quad (1.19)$$

where $^{14}\tau_c$ is expressed in years B.P. Here we do not use that convention and compute reservoir ages with the mean lifetime $1/\lambda$. Conversion from one scale to the other is readily performed. The conventional radiocarbon age is lower than the radiocarbon age by $\simeq 3\%$.

The ocean radiocarbon inventory is computed as

$$N_A \, ^{14}\text{R}_{\text{oxa}} \overline{C_T} \left(\int_{\Omega} ^{14}\text{R} d\Omega \right) / 10^{26}, \quad (1.20)$$

where N_A is the Avogadro's number ($N_A = 6.022 \times 10^{23}$ at/mol), $^{14}\text{R}_{\text{oxa}}$ is the oxalic acid radiocarbon standard ($^{14}\text{R}_{\text{oxa}} = 1.176 \times 10^{-12}$; [Stuiver and Polach, 1977](#)), and Ω is the ocean volume. Bomb ^{14}C inventories are traditionally reported in units of 10^{26} atoms, hence the denominator in (1.20).

All transformations from second to year, and inversely, are performed with the help of the physical constant `RSIYEA` the sidereal year length expressed in seconds[†].

The global transfer velocities represent time-averaged[‡] global integrals of the transfer rates:

$$\overline{\kappa_{\text{CO}_2}} = \int_S \kappa_{\text{CO}_2} dS \quad \text{and} \quad \overline{\kappa_R} = \int_S \kappa_R dS \quad (1.21)$$

1.4.4. PISCES biogeochemical model

PISCES is a biogeochemical model which simulates the lower trophic levels of marine ecosystem (phytoplankton, microzooplankton and mesozooplankton) and the biogeochemical cycles of carbon and of the main nutrients (P, N, Fe, and Si). The model is intended to be used for both regional and global configurations at high or low spatial resolutions as well as for short-term (seasonal, interannual) and long-term (climate change, paleoceanography) analyses. Two versions of PISCES are available in NEMO v4.0 :

PISCES-v2, by setting in `namelist_pisces_ref` `ln_p4z` to true, can be seen as one of the many Monod models ([Monod, 1958](#)). It assumes a constant Redfield ratio and phytoplankton growth depends on the external concentration in nutrients. There are twenty-four prognostic variables (tracers) including two phytoplankton compartments (diatoms and nanophytoplankton), two zooplankton size-classes (microzooplankton and mesozooplankton) and a description of the carbonate chemistry. Formulations in PISCES-v2 are based on a mixed Monod/Quota formalism: On one hand,

[†]The variable (`NYEAR_LEN`) which reports the length in days of the previous/current/future year (see `oce_trc.F90`) is not a constant.

[‡]the actual duration is set in `iodef.xml`

stoichiometry of C/N/P is fixed and growth rate of phytoplankton is limited by the external availability in N, P and Si. On the other hand, the iron and silicium quotas are variable and growth rate of phytoplankton is limited by the internal availability in Fe. Various parameterizations can be activated in PISCES-v2, setting for instance the complexity of iron chemistry or the description of particulate organic materials.

PISCES-QUOTA has been built on the PISCES-v2 model described in [Aumont et al. \(2015\)](#). PISCES-QUOTA has thirty-nine prognostic compartments. Phytoplankton growth can be controlled by five modeled limiting nutrients: Nitrate and Ammonium, Phosphate, Silicate and Iron. Five living compartments are represented: Three phytoplankton size classes/groups corresponding to picophytoplankton, nanophytoplankton and diatoms, and two zooplankton size classes which are microzooplankton and mesozooplankton. For phytoplankton, the prognostic variables are the carbon, nitrogen, phosphorus, iron, chlorophyll and silicon biomasses (the latter only for diatoms). This means that the N/C, P/C, Fe/C and Chl/C ratios of both phytoplankton groups as well as the Si/C ratio of diatoms are prognostically predicted by the model. Zooplankton are assumed to be strictly homeostatic (e.g., [Sterner and Elser, 2003](#); [Woods and Wilson, 2013](#); [Meunier et al., 2014](#)). As a consequence, the C/N/P/Fe ratios of these groups are maintained constant and are not allowed to vary. In PISCES, the Redfield ratios C/N/P are set to 122/16/1 ([Takahashi et al., 1985](#)) and the -O/C ratio is set to 1.34 ([Körtzinger et al., 2001](#)). No silicified zooplankton is assumed. The bacterial pool is not yet explicitly modeled.

There are three non-living compartments: Semi-labile dissolved organic matter, small sinking particles, and large sinking particles. As a consequence of the variable stoichiometric ratios of phytoplankton and of the stoichiometric regulation of zooplankton, elemental ratios in organic matter cannot be supposed constant anymore as that was the case in PISCES-v2. Indeed, the nitrogen, phosphorus, iron, silicon and calcite pools of the particles are now all explicitly modeled. The sinking speed of the particles is not altered by their content in calcite and biogenic silicate ("The ballast effect", ([Honjo, 1996](#); [Armstrong et al., 2001](#))). The latter particles are assumed to sink at the same speed as the large organic matter particles. All the non-living compartments experience aggregation due to turbulence and differential settling as well as Brownian coagulation for DOM.

1.4.5. MY_TRC interface for coupling external BGC models

The NEMO-TOP has only one built-in biogeochemical model - PISCES - but there are several BGC models - MEDUSA, ERSEM, BFM or ECO3M - which are meant to be coupled with the NEMO dynamics. Therefore it was necessary to provide to the users a framework for easily add their own BGC model, that can be a single passive tracer. The generalized interface is pivoted on MY_TRC module that contains template files to build the coupling between NEMO and any external BGC model. The call to MY_TRC is activated by setting `ln_my_trc = .true.` in namelist `namtrc`

The following 6 fortran files are available in MY_TRC with the specific purposes here described.

- `par_my_trc.F90` : This module allows to define additional arrays and public variables to be used within the MY_TRC interface
- `trcini_my_trc.F90` : Here are initialized user defined namelists and the call to the external BGC model initialization procedures to populate general tracer array (trn and trb). Here are also likely to be defined support arrays related to system metrics that could be needed by the BGC model.
- `trcnam_my_trc.F90` : This routine is called at the beginning of `trcini_my_trc` and should contain the initialization of additional namelists for the BGC model or user-defined code.
- `trcsms_my_trc.F90` : The routine performs the call to Boundary Conditions and its main purpose is to contain the Source-Minus-Sinks terms due to the biogeochemical processes of the external model. Be aware that lateral boundary conditions are applied in `trcnxt` routine. IMPORTANT: the routines to compute the light penetration along the water column and the tracer vertical sinking should be defined/called in here, as generalized modules are still missing in the code.
- `trcice_my_trc.F90` : Here it is possible to prescribe the tracers concentrations in the seaice that will be used as boundary conditions when ice melting occurs (`nn_ice_tr = 1` in `namtrc_ice`). See e.g. the correspondent PISCES subroutine.
- `trcwri_my_trc.F90` : This routine performs the output of the model tracers using IOM module (see Manual Chapter Output and Diagnostics). It is possible to place here the output of additional variables produced by the model, if not done elsewhere in the code, using the call to `iom_put`.

1.5. The Offline Option

```

!-----
&namdta_dyn      !  offline ocean input files                                (OFF_SRC only)
!-----
ln_dynrnf        =  .false.      !  runoffs option enabled (T) or not (F)
ln_dynrnf_depth  =  .false.      !  runoffs is spread in vertical (T) or not (F)
! fwbcorr        =  3.786e-06    !  annual global mean of empmr for ssh correction

cn_dir          =  './'          !  root directory for the ocean data location

↳ !-----!-----!-----!-----!-----!-----!-----!
!      ! file name      ! frequency (hours) ! variable ! time interp.! clim ! 'yearly'/ !
↳ weights filename ! rotation ! land/sea mask !
!      !      !      ! (if <0 months) ! name      !      (logical) ! (T/F) ! 'monthly' !
↳ ! pairing ! filename !
sn_tem         =  'dyna_grid_T'  ,      120.      , 'votemper' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_sal         =  'dyna_grid_T'  ,      120.      , 'vosaline' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_mld         =  'dyna_grid_T'  ,      120.      , 'somixhgt' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_emp         =  'dyna_grid_T'  ,      120.      , 'sowafgup' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_fmfl        =  'dyna_grid_T'  ,      120.      , 'iowafgup' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_ice         =  'dyna_grid_T'  ,      120.      , 'soicecov' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_qsr         =  'dyna_grid_T'  ,      120.      , 'soshfldo' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_wnd         =  'dyna_grid_T'  ,      120.      , 'sowindsp' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_uwd         =  'dyna_grid_U'  ,      120.      , 'uocetr_eff' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_vwd         =  'dyna_grid_V'  ,      120.      , 'vocetr_eff' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_wwd         =  'dyna_grid_W'  ,      120.      , 'wocetr_eff' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_avt         =  'dyna_grid_W'  ,      120.      , 'voddmavs' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_ubl         =  'dyna_grid_U'  ,      120.      , 'sobblcox' , .true. , .true. , 'yearly' , ''
↳ , ''
sn_vbl         =  'dyna_grid_V'  ,      120.      , 'sobblcoy' , .true. , .true. , 'yearly' , ''
↳ , ''
/

```

Coupling passive tracers offline with NEMO requires precomputed physical fields from OGCM. Those fields are read from files and interpolated on-the-fly at each model time step. At least the following dynamical parameters should be absolutely passed to the transport : ocean velocities, temperature, salinity, mixed layer depth and for ecosystem models like PISCES, sea ice concentration, short wave radiation at the ocean surface, wind speed (or at least, wind stress). The so-called offline mode is useful since it has lower computational costs for example to perform very longer simulations - about 3000 years - to reach equilibrium of CO₂ sinks for climate-carbon studies.

The offline interface is located in the code repository : `<repository>/src/OFF/`. It is activated by adding the CPP key `key_offline` to the CPP keys list. There are two specific routines for the Offline code :

- `dtadyn.F90` : this module allows to read and compute the dynamical fields at each model time-step
- `nemogcm.F90` : a degraded version of the main `nemogcm.F90` code of NEMO to manage the time-stepping

2.1. Setting up a passive tracer configuration

```

!-----
&namtrc      !  tracers definition
!-----
  jp_bgc      = 0          !  Number of passive tracers of the BGC model
  !
  ln_pisces   = .false.    !  Run PISCES BGC model
  ln_my_trc   = .false.    !  Run MY_TRC BGC model
  ln_age      = .false.    !  Run the sea water age tracer
  ln_cfc11    = .false.    !  Run the CFC11 passive tracer
  ln_cfc12    = .false.    !  Run the CFC12 passive tracer
  ln_sf6      = .false.    !  Run the SF6 passive tracer
  ln_c14      = .false.    !  Run the Radiocarbon passive tracer
  !
  ln_trcdta   = .false.    !  Initialisation from data input file (T) or not (F)
  ln_trcdmp   = .false.    !  add a damping termn (T) or not (F)
  ln_trcdmp_clo = .false.  !  damping term (T) or not (F) on closed seas
  !
  jp_dia3d    = 0          !  Number of 3D diagnostic variables
  jp_dia2d    = 0          !  Number of 2D diagnostic variables
  !-----!-----!-----!-----!
  ! name ! title of the field ! units ! init from file !
! sn_tracer(1) = 'tracer ', 'Tracer Concentration', '-', .false.
/

```

The usage of TOP is activated

- by including in the configuration definition the component TOP_SRC
- by adding the macro *key_top* in the configuration cpp file

As an example, the user can refer to already available configurations in the code, GYRE_PISCES being the NEMO biogeochemical demonstrator and GYRE_BFM to see the required configuration elements to couple with an external biogeochemical model (see also section §1.4).

Note that, since version 4.0, TOP interface core functionalities are activated by means of logical keys and all submodules preprocessing macros from previous versions were removed.

There are only three specific keys remaining in TOP

- *key_top* : to enables passive tracer module
- *key_trdtrc* and *key_trdmxl_trc* : trend computation for tracers

For a remind, the revisited structure of TOP interface now counts for five different modules handled in *namelist_top* :

- **PISCES**, default BGC model
- **MY_TRC**, template for creation of new modules couplings (maybe run a single passive tracer)
- **CFC**, inert carbon tracers dynamics (CFC11,CFC12,SF6) Updated with OMIP-BGC guidelines (Orr et al, 2016)
- **C14**, radiocarbon passive tracer
- **AGE**, water age tracking revised implementation

The modular approach was implemented also in the definition of the total number of passive tracers (*jptra*). This results from to user setting from the namelist *namtrc*

2.2. TOP Tracer Initialisation

2.3. TOP Boundaries Conditions

3.1. TOP synthetic Workflow

3.1.1. Model initialization

3.1.2. Time marching procedure

3.2. Coupling an external BGC model using NEMO framework

The coupling with an external BGC model through the NEMO compilation framework can be achieved in different ways according to the degree of coding complexity of the Biogeochemical model, like e.g., the whole code is made only by one file or it has multiple modules and interfaces spread across several subfolders.

Beside the 6 core files of MY_TRC module, see (see , let's assume an external BGC model named "MYBGC" and constituted by a rather essential coding structure, likely few Fortran files. The new coupled configuration name is NEMO_MYBGC.

The best solution is to have all files (the modified MY_TRC routines and the BGC model ones) placed in a unique folder with root <MYBGCPATH> and to use the *makenemo* external readdressing of MY_SRC folder.

The coupled configuration listed in **cfg.txt** will look like

```
NEMO_MYBGC OPA_SRC TOP_SRC
```

and the related **cpp_MYBGC.fcm** content will be

```
bld::tool::fppkeys    key_iomput key_mpp_mpi key_top
```

the compilation with *makenemo* will be executed through the following syntax

```
makenemo -n NEMO_MYBGC -m <arch_my_machine> -j 8 -e <MYBGCPATH>
```

```
bld::tool::fppkeys    key_iomput key_mpp_mpi key_top

src::MYBGC::initialization    <MYBGCPATH>/initialization
src::MYBGC::pelagic           <MYBGCPATH>/pelagic
src::MYBGC::benthic           <MYBGCPATH>/benthic

bld::pp::MYBGC             1
bld::tool::fppflags::MYBGC    %FPPFLAGS
bld::tool::fppkeys          %bld::tool::fppkeys MYBGC_MACROS
```



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A "model life" is more than ten years. Its software, composed of a few hundred modules, is used by many people who are scientists or students and do not necessarily know every aspect of computing very well. Moreover, a well thought-out program is easier to read and understand, less difficult to modify, produces fewer bugs and is easier to maintain. Therefore, it is essential that the model development follows some rules:

- well planned and designed
- well written
- well documented (both on- and off-line)
- maintainable
- easily portable
- flexible.

To satisfy part of these aims, *NEMO* is written with a coding standard which is close to the ECMWF rules, named DOCTOR (?). These rules present some advantages like:

- to provide a well presented program
- to use rules for variable names which allow recognition of their type (integer, real, parameter, local or shared variables, etc.).

This facilitates both the understanding and the debugging of an algorithm.

A.1. Introduction

This document describes conventions used in *NEMO* coding and suggested for its development. The objectives are to offer a guide to all readers of the *NEMO* code, and to facilitate the work of all the developers, including the validation of their developments, and eventually the implementation of these developments within the *NEMO* platform.

A first approach of these rules can be found in the code in `./src/OCE/module_example` where all the basics coding conventions are illustrated. More details can be found below.

This work is based on the coding conventions in use for the Community Climate System Model *, the previous version of this document ("FORTRAN coding standard in the OPA System") and the expertise of the *NEMO* System Team. After a general overview below, this document will describe:

- The style rules, *i.e.* the syntax, appearance and naming conventions chosen to improve readability of the code;
- The content rules, *i.e.* the conventions to improve the reliability of the different parts of the code;
- The package rules to go a step further by improving the reliability of the whole and interfaces between routines and modules.

A.2. Overview and general conventions

NEMO has 3 major components: ocean dynamics (`./src/OCE`), sea-ice (`./src/ICE`) and marine biogeochemistry (`./src/MBG`). In each directory, one will find some FORTRAN files and/or subdirectories, one per functionality of the code: `./src/OCE/BDY` (boundaries), `./src/OCE/DIA` (diagnostics), `./src/OCE/DOM` (domain), `./src/OCE/DYN` (dynamics), `./src/OCE/LDF` (lateral diffusion), etc...

All name are chosen to be as self-explanatory as possible, in English, all prefixes are 3 digits.

English is used for all variables names, comments, and documentation.

Physical units are MKS. The only exception to this is the temperature, which is expressed in degrees Celsius, except in bulk formulae and part of SI³ sea-ice model where it is in Kelvin. See `./src/OCE/DOM/physcst.F90` files for conversions.

*UCAR conventions

A.3. Architecture

Within each directory, organisation of files is driven by orthogonality, *i.e.* one functionality of the code is intended to be in one and only one directory, and one module and all its related routines are in one file. The functional modules are:

- SBC surface module
- IOM management of the I/O
- NST interface to AGRIF (nesting model) for dynamics and biogeochemistry
- OBC, BDY management of structured and unstructured open boundaries
- C1D 1D (vertical) configuration for dynamics, sea-ice and biogeochemistry
- OFF off-line module: passive tracer or biogeochemistry alone
- ...

For example, the file *domain.F90* contains the module `domain` and all the subroutines related to this module (`dom_init`, `dom_nam`, `dom_ctl`).

A.4. Style rules

A.4.1. Argument list format

Routine argument lists will contain a maximum 5 variables per line, whilst continuation lines can be used. This applies both to the calling routine and the dummy argument list in the routine being called. The purpose is to simplify matching up the arguments between caller and callee.

```
SUBROUTINE tra_adv_eiv( kt, pun, pvn, pwn )
    CALL tra_adv_eiv( kt, zun, zvn, zwn )
```

A.4.2. Array syntax

Except for long loops (see below), array notation should be used if possible. To improve readability the array shape must be shown in brackets, *e.g.*:

```
onedarraya(:) = onedarrayb(:) + onedarrayc(:)
twodarray(:, :) = scalar * another twodarray(:, :)
```

When accessing sections of arrays, for example in finite difference equations, do so by using the triplet notation on the full array, *e.g.*:

```
twodarray(:, 2:len2) = scalar &
& * ( twodarray2(:, 1:len2-1) &
& - twodarray2(:, 2:len2) )
```

For long, complicated loops, explicitly indexed loops should be preferred. In general when using this syntax, the order of the loops indices should reflect the following scheme (for best usage of data locality):

```
DO jk = 1, jpk
  DO jj = 1, jpj
    DO ji = 1, jpi
      threedarray(ji, jj, jk) = ...
    END DO
  END DO
END DO
```

A.4.3. Case

All FORTRAN keywords are in capital: `DIMENSION`, `WRITE`, `DO`, `END DO`, `NAMelist`, ... All other parts of the *NEMO* code will be written in lower case.

A.4.9. Indentation

Code as well as comment lines within loops, if-blocks, continuation lines, **MODULE** or **SUBROUTINE** statements will be indented 3 characters for readability (except for **CONTAINS** that remains at first column).

```

MODULE mod1
  REAL(wp) xx
CONTAINS
  SUBROUTINE sub76( px, py, pz, pw, pa, &
                  & pb, pc, pd, pe      )
    <instruction>
  END SUBROUTINE sub76
END MODULE mod1

```

A.4.10. Loops

Loops, if explicit, should be structured with the do-end do construct as opposed to numbered loops. Nevertheless non-numeric labels can be used for a big iterative loop of a recursive algorithm. In the case of a long loop, a self-descriptive label can be used (*i.e.* not just a number).

A.4.11. Naming Conventions: files

A file containing a module will have the same name as the module it contains (because dependency rules used by "make" programs are based on file names).[†]

A.4.12. Naming Conventions: modules

Use a meaningful English name and the "3 letters" naming convention: first 3 letters for the code section, and last 3 to describe the module. For example, *zdf*tke, where "zdf" stands for vertical diffusion, and "tke" for turbulent kinetic energy. Note that by implication multiple modules are not allowed in a single file. The use of common blocks is deprecated in FORTRAN90 and their use in *NEMO* is strongly discouraged. Modules are a better way to declare static data. Among the advantages of modules is the ability to freely mix data of various types, and to limit access to contained variables through the use of the **ONLY** and **PRIVATE** attributes.

A.4.13. Naming Conventions: variables

All variable should be named as explicitly as possible in English. The naming convention concerns prefix letters of these name, in order to identify the variable type and status.

Never use a FORTRAN keyword as a routine or variable name.

The table below lists the starting letter(s) to be used for variable naming, depending on their type and status:

A.4.14. Operators

Use of the operators `<`, `>`, `<=`, `>=`, `==`, `/=` is strongly recommended instead of their deprecated counterparts (`.lt.`, `.gt.`, `.le.`, `.ge.`, `.eq.`, `.ne.`). The motivation is readability. In general use the notation:

`< Blank >< Operator >< Blank >`

A.4.15. Pre processor

Where the use of a language pre-processor is required, it will be the C pre-processor (`cpp`).

The `cpp` key is the main feature used, allowing to ignore some useless parts of the code at compilation step.

The advantage is to reduce the memory use; the drawback is that compilation of this part of the code isn't checked.

The `cpp` key feature should only be used for a few limited options, if it reduces the memory usage. In all cases, a logical variable and a FORTRAN **IF** should be preferred. When using a `cpp` key `key_optionname`, a corresponding logical variable `lk_optionname` should be declared to allow FORTRAN **IF** tests in the code and a FORTRAN module with the same name (*i.e.* `optionname.F90`) should be defined. This module is the only place where a "if defined" command appears, selecting either the whole FORTRAN code or a dummy module. For example, the TKE vertical physics, the module name is `zdf`tke.F90, the CPP key is `key_zdf`tke and the associated logical is `lk_zdf`tke.

The following syntax:

[†]For example, if routine A "USE"s module B, then "make" must be told of the dependency relation which requires B to be compiled before A. If one can assume that module B resides in file B.o, building a tool to generate this dependency rule (*e.g.* A.o: B.o) is quite simple. Put another way, it is difficult (to say nothing of CPU-intensive) to search an entire source tree to find the file in which module B resides for each routine or module which "USE"s B.

Type / Status	integer	real	logical	character	double precision	complex
public or module variable	m n <i>but not nn_</i>	a b e f g h o q to x <i>but not fs rn_</i>	l <i>but not lp ld ll ln_</i>	c <i>but not cp cd cl cn_</i>	d <i>but not dp dd dl dn_</i>	y <i>but not yp yd yl</i>
dummy argument	k <i>but not kf</i>	p <i>but not pp pf</i>	ld	cd	dd	yd
local variable	i	z	ll	cl	cd	yl
loop control	j <i>but not jp</i>					
parameter	jp	pp	lp	cp	dp	yp
namelist	nn_	rn_	ln_	cn_	dn_	
CPP macro	kf	sf				

```
#if defined key_optionname
!! Part of code conditionally compiled if cpp key key_optionname is active
#endif
```

Is to be used rather than the `#ifdef` abbreviate form since it may have conflicts with some Unix scripts.

Tests on cpp keys included in *NEMO* at compilation step:

- The CPP keys used are compared to the previous list of cpp keys (the compilation will stop if trying to specify a non-existing key)
- If a change occurs in the CPP keys used for a given experiment, the whole compilation phase is done again.

A.5. Content rules

A.5.1. Configurations

The configuration defines the domain and the grid on which *NEMO* is running. It may be useful to associate a CPP key and some variables to a given configuration, although the part of the code changed under each of those keys should be minimized. As an example, the "ORCA2" configuration (global ocean, 2 degrees grid size) is associated with the cpp key `key_orca2` for which

```
cp_cfg = "orca"
jp_cfg = 2
```

A.5.2. Constants

Physical constants (*e.g.* π , gas constants) must never be hard-wired into the executable portion of a code. Instead, a mnemonically named variable or parameter should be set to the appropriate value, in the setup routine for the package. We realize that many parameterizations rely on empirically derived constants or fudge factors, which are not easy to name. In these cases it is not forbidden to leave such factors coded as "magic numbers" buried in executable code, but comments should be included referring to the source of the empirical formula. Hard-coded numbers should never be passed through argument lists.

A.5.3. Declaration for variables and constants

Rules

Variables used as constants should be declared with attribute `PARAMETER` and used always without copying to local variables, in order to prevent from using different values for the same constant or changing it accidentally.

- Usage of the `DIMENSION` statement or attribute is required in declaration statements

- The “:” notation is quite useful to show that this program unit declaration part is written in standard FORTRAN syntax, even if there are no attributes to clarify the declaration section. Always use the notation <blank>::<three blanks> to improve readability.
- Declare the length of a character variable using the **CHARACTER** (len=xxx) syntax [‡]
- For all global data (in contrast to module data, that is all data that can be access by other module) must be accompanied with a comment field on the same line [§]. For example:

```
REAL(wp), DIMENSION(jpi,jpj,jpk) :: ua ! i-horizontal velocity (m/s)
```

Implicit None

All subroutines and functions will include an **IMPLICIT NONE** statement. Thus all variables must be explicitly typed. It also allows the compiler to detect typographical errors in variable names. For modules, one **IMPLICIT NONE** statement in the modules definition section is needed. This also removes the need to have **IMPLICIT NONE** statements in any routines that are **CONTAINS**'ed in the module. Improper data initialisation is another common source of errors [¶]. To avoid problems, initialise variables as close as possible to where they are first used.

Attributes

PRIVATE / PUBLIC: All resources of a module are **PUBLIC** by default. A reason to store multiple routines and their data in a single module is that the scope of the data defined in the module can be limited to the routines which are in the same module. This is accomplished with the **PRIVATE** attribute.

INTENT: All dummy arguments of a routine must include the **INTENT** clause in their declaration in order to improve control of variables in routine calls.

A.5.4. Headers

Prologues are not used in *NEMO* for now, although it may become an interesting tool in combination with ProTeX auto documentation script in the future. Rules to code the headers and layout of a module or a routine are illustrated in the example module available with the code: `./src/OCE/module_example`

A.5.5. Interface blocks

Explicit interface blocks are required between routines if optional or keyword arguments are to be used. They also allow the compiler to check that the type, shape and number of arguments specified in the **CALL** are the same as those specified in the subprogram itself. FORTRAN 95 compilers can automatically provide explicit interface blocks for routines contained in a module.

A.5.6. I/O Error Conditions

I/O statements which need to check an error condition will use the `iostat=<integer variable>` construct instead of the outmoded `end=` and `err=`.

Note that a 0 value means success, a positive value means an error has occurred, and a negative value means the end of record or end of file was encountered.

A.5.7. PRINT - ASCII output files

Output listing and errors are directed to `numout` logical unit =6 and produces a file called *ocean.output* (use `ln_prt` to have one output per process in MPP). Logical `lwp` variable allows for less verbose outputs. To output an error from a routine, one can use the following template:

```
IF( nstop /= 0 .AND. lwp ) THEN ! error print
  WRITE(numout,cform_err)
  WRITE(numout,*) nstop, ' error have been found'
ENDIF
```

[‡]The len specifier is important because it is possible to have several kinds for characters (e.g. Unicode using two bytes per character, or there might be a different kind for Japanese e.g. NEC).

[§]This allows a easy research of where and how a variable is declared using the unix command: “`grep var *90 | grep !:`”.

[¶]A variable could contain an initial value you did not expect. This can happen for several reasons, e.g. the variable has never been assigned a value, its value is outdated, memory has been allocated for a pointer but you have forgotten to initialise the variable pointed to.

A.5.8. Precision

Parameterizations should not rely on vendor-supplied flags to supply a default floating point precision or integer size. The F95 `KIND` feature should be used instead. In order to improve portability between 32 and 64 bit platforms, it is necessary to make use of kinds by using a specific module `./src/OCE/par_kind.F90` declaring the "kind definitions" to obtain the required numerical precision and range as well as the size of `INTEGER`. It should be noted that numerical constants need to have a suffix of `_kindvalue` to have the according size.

Thus `wp` being the "working precision" as declared in `./src/OCE/par_kind.F90`, declaring real array `zpc` will take the form:

```
REAL(wp), DIMENSION(jpi,jpj,jpk) :: zpc      ! power consumption
```

A.5.9. Structures

The `TYPE` structure allowing to declare some variables is more often used in *NEMO*, especially in the modules dealing with reading fields, or interfaces. For example:

```
! Definition of a tracer as a structure
TYPE PTRACER
  CHARACTER(len = 20) :: sname ! short name
  CHARACTER(len = 80) :: lname ! long name
  CHARACTER(len = 20) :: unit  ! unit
  LOGICAL              :: lini  ! read in a file or not
  LOGICAL              :: lsav  ! ouput the tracer or not
END TYPE PTRACER

TYPE(PTRACER), DIMENSION(jptra) :: tracer
```

Missing rule on structure name??

A.6. Packages coding rules

A.6.1. Bounds checking

NEMO is able to run when an array bounds checking option is enabled (provided the `cpp` key `key_vectopt_loop` is not defined).

Thus, constructs of the following form are disallowed:

```
REAL(wp) :: arr(1)
```

where "arr" is an input argument into which the user wishes to index beyond 1. Use of the (*) construct in array dimensioning is forbidden also because it effectively disables array bounds checking.

A.6.2. Communication

A package should refer only to its own modules and subprograms and to those intrinsic functions included in the Fortran standard.

All communication with the package will be through the argument list or namelist input. ^{||}

A.6.3. Error conditions

When an error condition occurs inside a package, a message describing what went wrong will be printed (see `PRINT - ASCII` output files). The name of the routine in which the error occurred must be included. It is acceptable to terminate execution within a package, but the developer may instead wish to return an error flag through the argument list, see *stpctl.F90*.

^{||}The point behind this rule is that packages should not have to know details of the surrounding model data structures, or the names of variables outside of the package. A notable exception to this rule is model resolution parameters. The reason for the exception is to allow compile-time array sizing inside the package. This is often important for efficiency.

A.6.4. Memory management

The main action is to identify and declare which arrays are **PUBLIC** and which are **PRIVATE**.

As of version 3.3.1 of *NEMO*, the use of static arrays (size fixed at compile time) has been deprecated. All module arrays are now declared **ALLOCATABLE** and allocated in either the `<module_name>_alloc()` or `<module_name>_init()` routines. The success or otherwise of each **ALLOCATE** must be checked using the `stat=<integer variable>` optional argument.

In addition to arrays contained within modules, many routines in *NEMO* require local, “workspace” arrays to hold the intermediate results of calculations. In previous versions of *NEMO*, these arrays were declared in such a way as to be automatically allocated on the stack when the routine was called. An example of an automatic array is:

```
SUBROUTINE sub(n)
  REAL :: a(n)
  ...
END SUBROUTINE sub
```

The downside of this approach is that the program will crash if it runs out of stack space and the reason for the crash might not be obvious to the user.

Therefore, as of version 3.3.1, the use of automatic arrays is deprecated. Instead, a new module, *wrk_nemo.F90*, has been introduced which contains 1-,2-,3- and 4-dimensional workspace arrays for use in subroutines. These workspace arrays should be used in preference to declaring new, local (allocatable) arrays whenever possible. The only exceptions to this are when workspace arrays with lower bounds other than 1 and/or with extent(s) greater than those in the *wrk_nemo.F90* module are required.

The 2D, 3D and 4D workspace arrays in *wrk_nemo.F90* have extents `jpi`, `jpj`, `jpk` and `jpts` (x , y , z and tracers) in the first, second, third and fourth dimensions, respectively. The 1D arrays are allocated with extent $\text{MAX}(jpi \times jpj, jpk \times jpj, jpi \times jpk)$.

The **REAL** (`KIND = wp`) workspace arrays in *wrk_nemo.F90* are named e.g. `wrk_1d_1`, `wrk_4d_2` etc. and should be accessed by USE'ing the *wrk_nemo.F90* module. Since these arrays are available to any routine, some care must be taken that a given workspace array is not already being used somewhere up the call stack. To help with this, *wrk_nemo.F90* also contains some utility routines; `wrk_in_use()` and `wrk_not_released()`. The former first checks that the requested arrays are not already in use and then sets internal flags to show that they are now in use. The `wrk_not_released()` routine un-sets those internal flags. A subroutine using this functionality for two, 3D workspace arrays named `zwrk1` and `zwrk2` will look something like:

```
SUBROUTINE sub()
  USE wrk_nemo, ONLY: wrk_in_use, wrk_not_released
  USE wrk_nemo, ONLY: zwrk1 => wrk_3d_5, zwrk2 => wrk_3d_6
  !
  IF(wrk_in_use(3, 5,6) THEN
    CALL ctl_stop('sub: requested workspace arrays unavailable.')
    RETURN
  END IF
  ...
  ...
  IF(wrk_not_released(3, 5,6) THEN
    CALL ctl_stop('sub: failed to release workspace arrays.')
  END IF
  !
END SUBROUTINE sub
```

The first argument to each of the utility routines is the dimensionality of the required workspace (1–4). Following this there must be one or more integers identifying which workspaces are to be used/released. Note that, in the interests of keeping the code as simple as possible, there is no use of **POINTERS** etc. in the *wrk_nemo.F90* module. Therefore it is the responsibility of the developer to ensure that the arguments to `wrk_in_use()` and `wrk_not_released()` match the workspace arrays actually being used by the subroutine.

If a workspace array is required that has extent(s) less than those of the arrays in the *wrk_nemo.F90* module then the advantages of implicit loops and bounds checking may be retained by defining a pointer to a sub-array as follows:

```
SUBROUTINE sub()
  USE wrk_nemo, ONLY: wrk_in_use, wrk_not_released
  USE wrk_nemo, ONLY: wrk_3d_5
  !
  REAL(wp), DIMENSION(:, :, :), POINTER :: zwrk1
  !
  IF(wrk_in_use(3, 5) THEN
    CALL ctl_stop('sub: requested workspace arrays unavailable.')
  !
```

```

    RETURN
  END IF
  !
  zwrk1 => wrk_3d_5(1:10,1:10,1:10)
  ...
END SUBROUTINE sub

```

Here, instead of “use associating” the variable `zwrk1` with the array `wrk_3d_5` (as in the first example), it is explicitly declared as a pointer to a 3D array. It is then associated with a sub-array of `wrk_3d_5` once the call to `wrk_in_use()` has completed successfully. Note that in F95 (to which *NEMO* conforms) it is not possible for either the upper or lower array bounds of the pointer object to differ from those of the target array.

In addition to the **REAL** (`KIND = wp`) workspace arrays, `wrk_nemo.F90` also contains 2D integer arrays and 2D REAL arrays with extent (`jpi, jpk`), *i.e.* `xz`. The utility routines for the integer workspaces are `iwrk_in_use()` and `iwrk_not_released()` while those for the `xz` workspaces are `wrk_in_use_xz()` and `wrk_not_released_xz()`.

Should a call to one of the `wrk_in_use()` family of utilities fail, an error message is printed along with a table showing which of the workspace arrays are currently in use. This should enable the developer to choose alternatives for use in the subroutine being worked on.

When compiling *NEMO* for production runs, the calls to `wrk_in_use()` / `wrk_not_released()` can be reduced to stubs that just return `.false.` by setting the cpp key `key_no_workspace_check`. These stubs may then be inlined (and thus effectively removed altogether) by setting appropriate compiler flags (*e.g.* “`-finline`” for the Intel compiler or “`-Q`” for the IBM compiler).

A.6.5. Optimisation

Considering the new computer architecture, optimisation cannot be considered independently from the computer type. In *NEMO*, portability is a priority, before any too specific optimisation.

Some tools are available to help: for vector computers, `key_vectopt_loop` allows to unroll a loop

A.6.6. Package attribute: **PRIVATE**, **PUBLIC**, **USE**, **ONLY**

Module variables and routines should be encapsulated by using the **PRIVATE** attribute. What shall be used outside the module can be declared **PUBLIC** instead. Use **USE** with the **ONLY** attribute to specify which of the variables, type definitions etc... defined in a module are to be made available to the using routine.

A.6.7. Parallelism using MPI

NEMO is written in order to be able to run on one processor, or on one or more using MPI (*i.e.* activating the cpp key `key_mpp_mpi`). The domain decomposition divides the global domain in cubes (see *NEMO* reference manual). Whilst coding a new development, the MPI compatibility has to be taken in account (see `./src/LBC/lib_mpp.F90`) and should be tested. By default, the `x-z` part of the decomposition is chosen to be as square as possible. However, this may be overridden by specifying the number of sub-domains in latitude and longitude in the `nammpp` section of the namelist file.

A.7. Features to be avoided

The code must follow the current standards of FORTRAN and ANSI C. In particular, the code should not produce any WARNING at compiling phase, so that users can be easily alerted of potential bugs when some appear in their new developments. Below is a list of features to avoid:

- **COMMON** block (use the declaration part of **MODULE** instead)
- **EQUIVALENCE** (use **POINTER** or derived data type instead to form data structure)
- Assigned and computed **GOTO** (use the **CASE** construct instead)
- Arithmetic **IF** statement (use the block **IF**, **ELSE**, **ELSEIF**, **ENDIF** or **SELECT CASE** construct instead)
- Labelled **DO** construct (use unlabelled **END DO** instead)
- **FORMAT** statement (use character parameters or explicit format- specifiers inside the **READ** or **WRITE** statement instead)
- **GOTO** and **CONTINUE** statements (use **IF**, **CASE**, **DO WHILE**, **EXIT** or **CYCLE** statements or a contained ?)

- **PAUSE**
- **ENTRY** statement: a sub-program must only have one entry point.
- **RETURN** is obsolete and so not necessary at the end of program units
- **FUNCTION** statement
- Avoid functions with side effects. **
- **DATA** and **BLOCK DATA** (use initialisers)

**First, the code is easier to understand, if you can rely on the rule that functions don't change their arguments. Second, some compilers generate more efficient code for PURE functions (in FORTRAN 95 there are the attributes PURE and ELEMENTAL), because they can store the arguments in different places. This is especially important on massive parallel and as well on vector machines.

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Namelist blocks

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N          &namnamtra_ldf..... 3          &namnamtrc_rad..... 3
          &namnamtrc_dmp..... 3
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Namelist parameters

Symbols	I	T
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